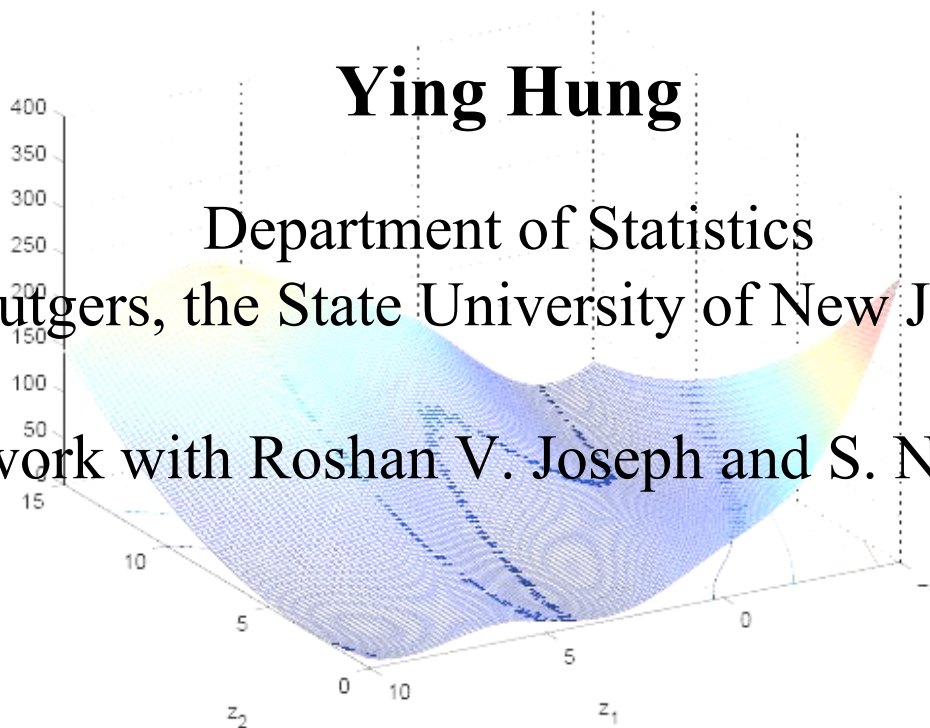


Design and Analysis of Computer Experiments with Branching and Nested Factors

Ying Hung

Department of Statistics
Rutgers, the State University of New Jersey

Joint work with Roshan V. Joseph and S. N. Melkote



Overview

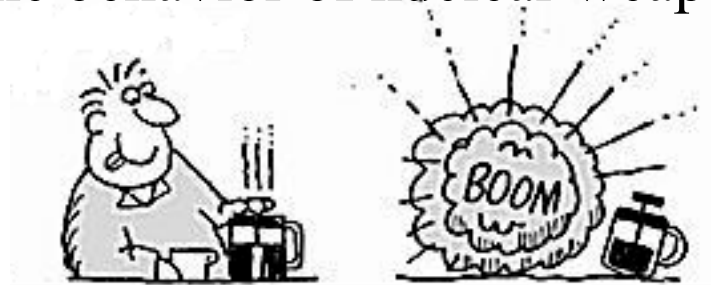
- ❖ **What is computer experiment?**
- ❖ **Computer experiments with branching and nested factors.**
 - ✓ **New class of designs.**
 - ✓ **Optimality criteria.**
 - ✓ **New metamodel.**

Introduction to Computer Experiments

- ❖ First computer experiments were conducted at Los Alamos National Laboratory to study the behavior of nuclear weapons.

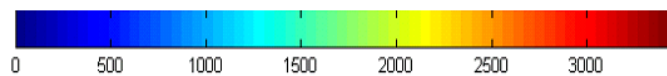
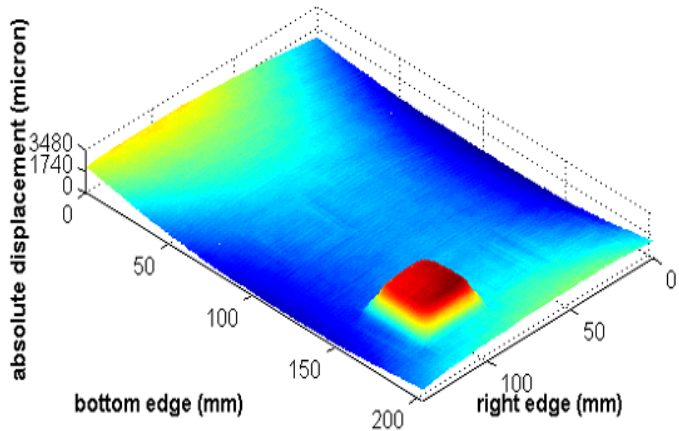
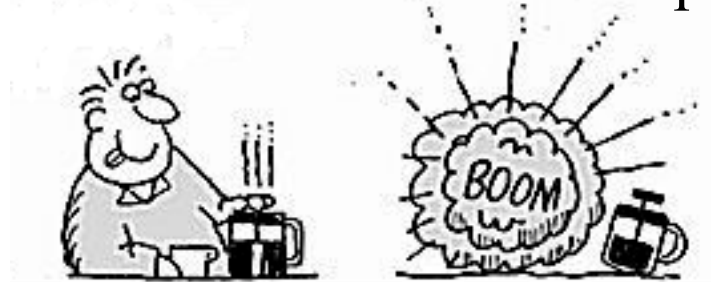
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- ❖ Computer experiments are becoming popular because many physical experiments are difficult or impossible to perform.

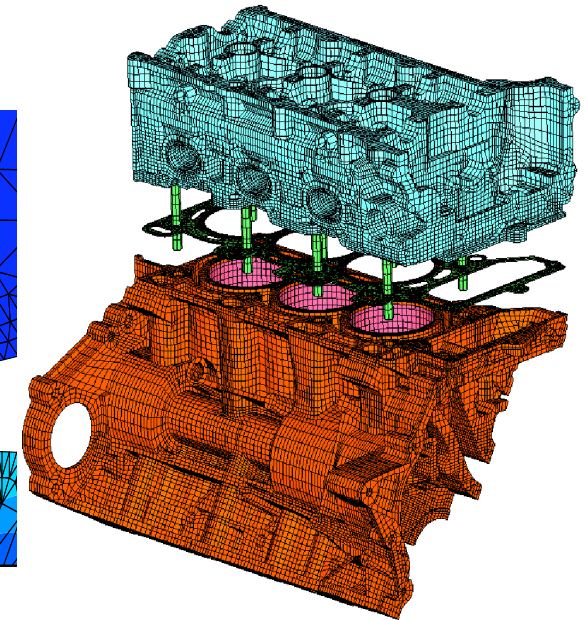
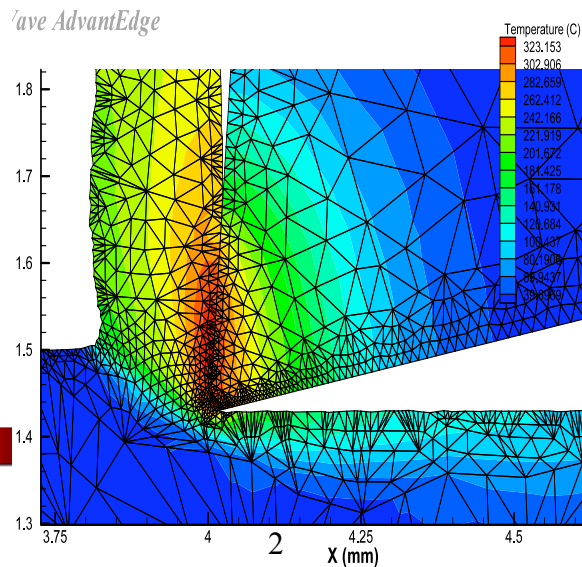


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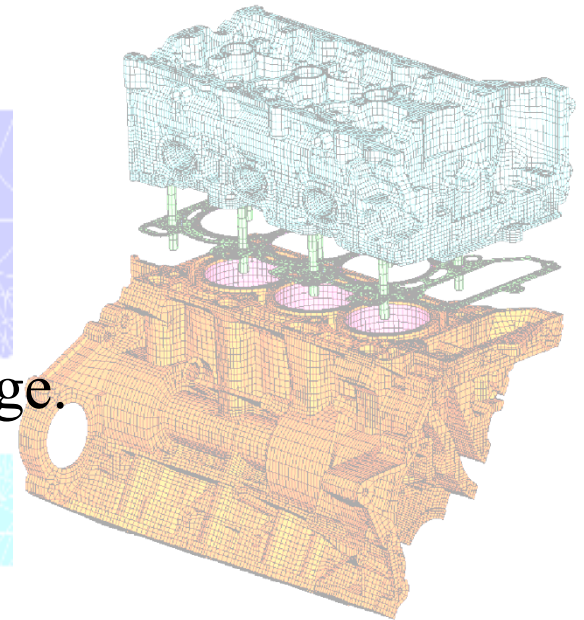
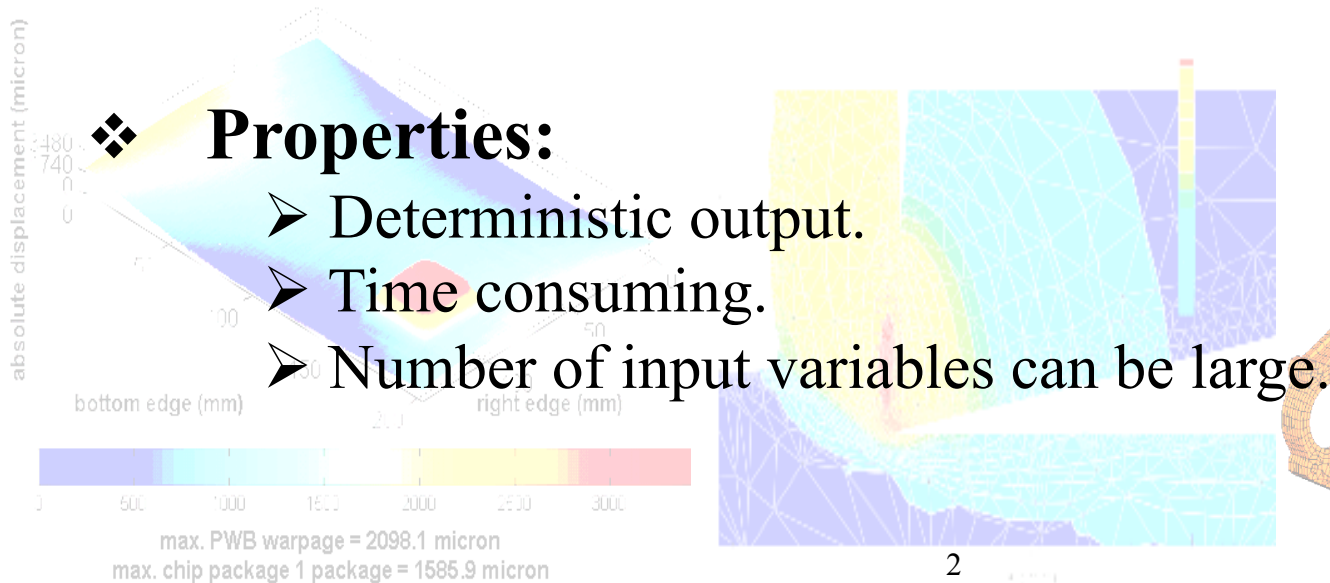
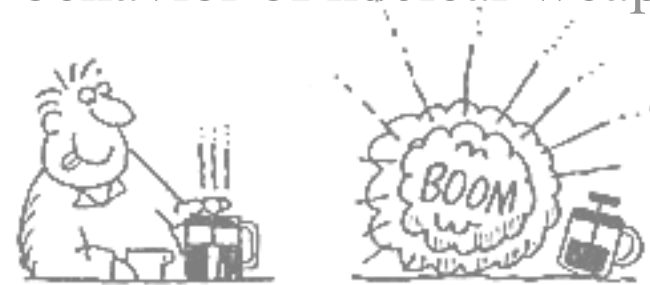


max. PWB warpage = 2098.1 micron
max. chip package 1 package = 1585.9 micron

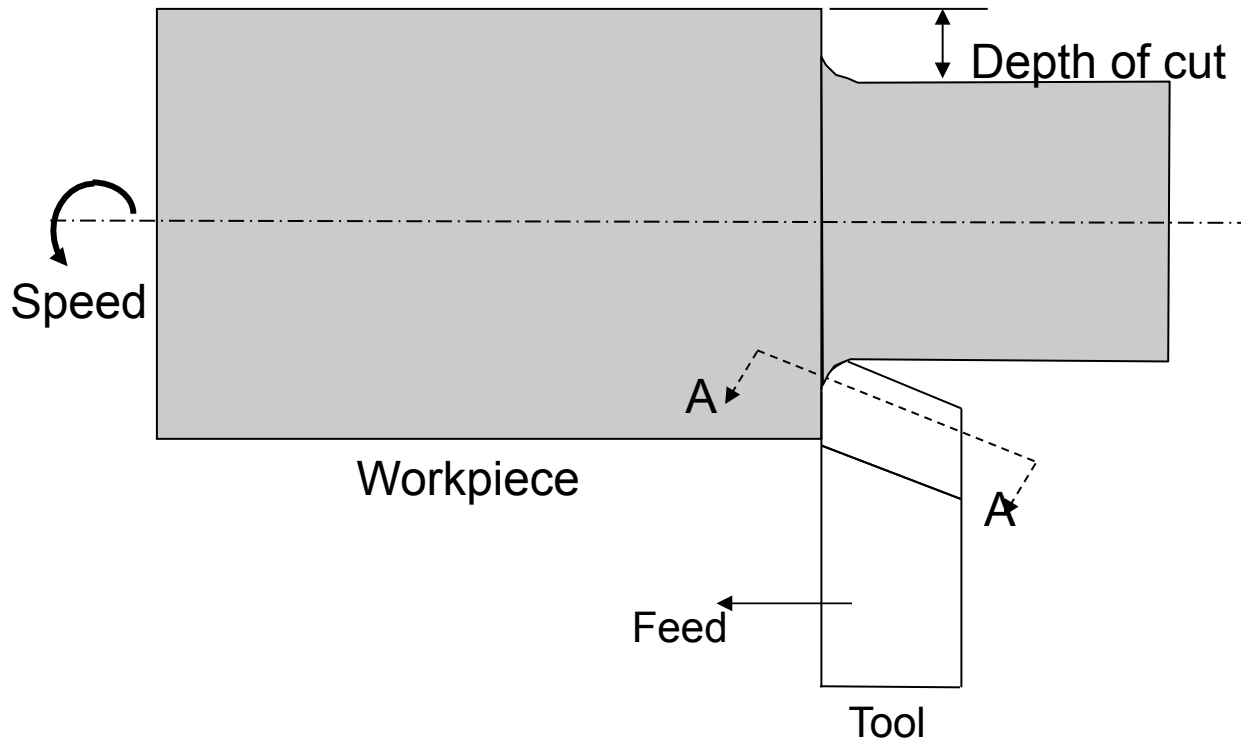


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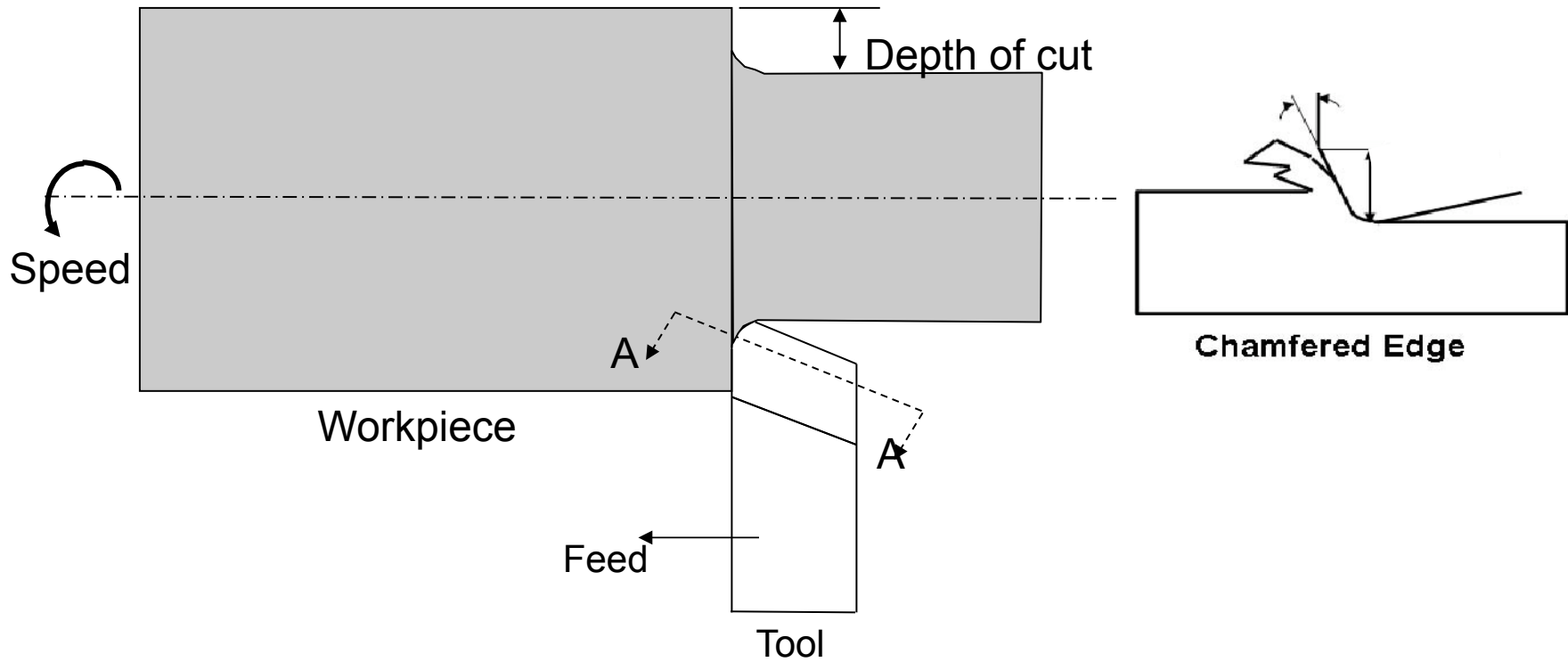


Motivating Example: Hard Turning



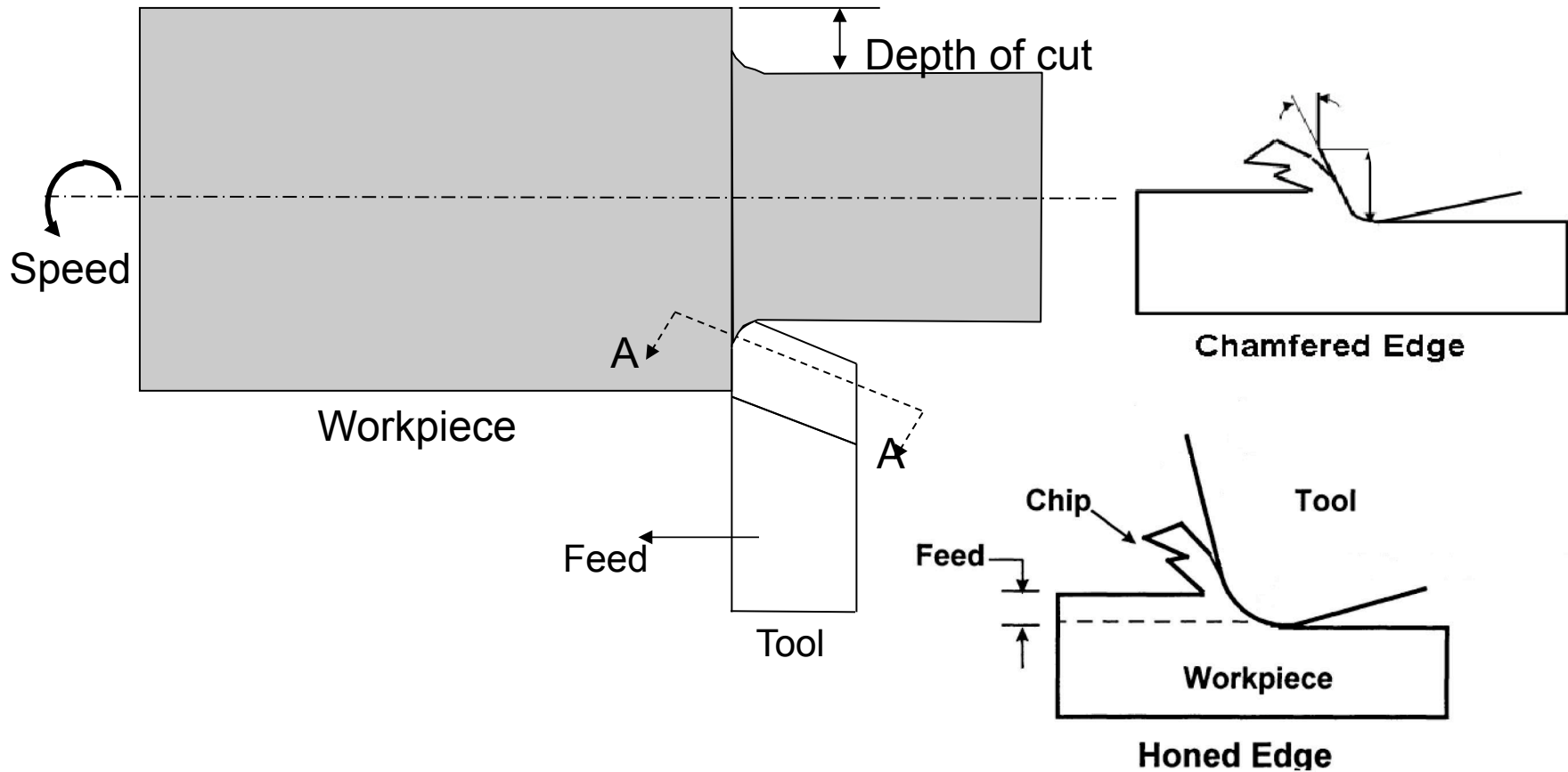
- Objective: minimize cutting force

Motivating Example: Hard Turning



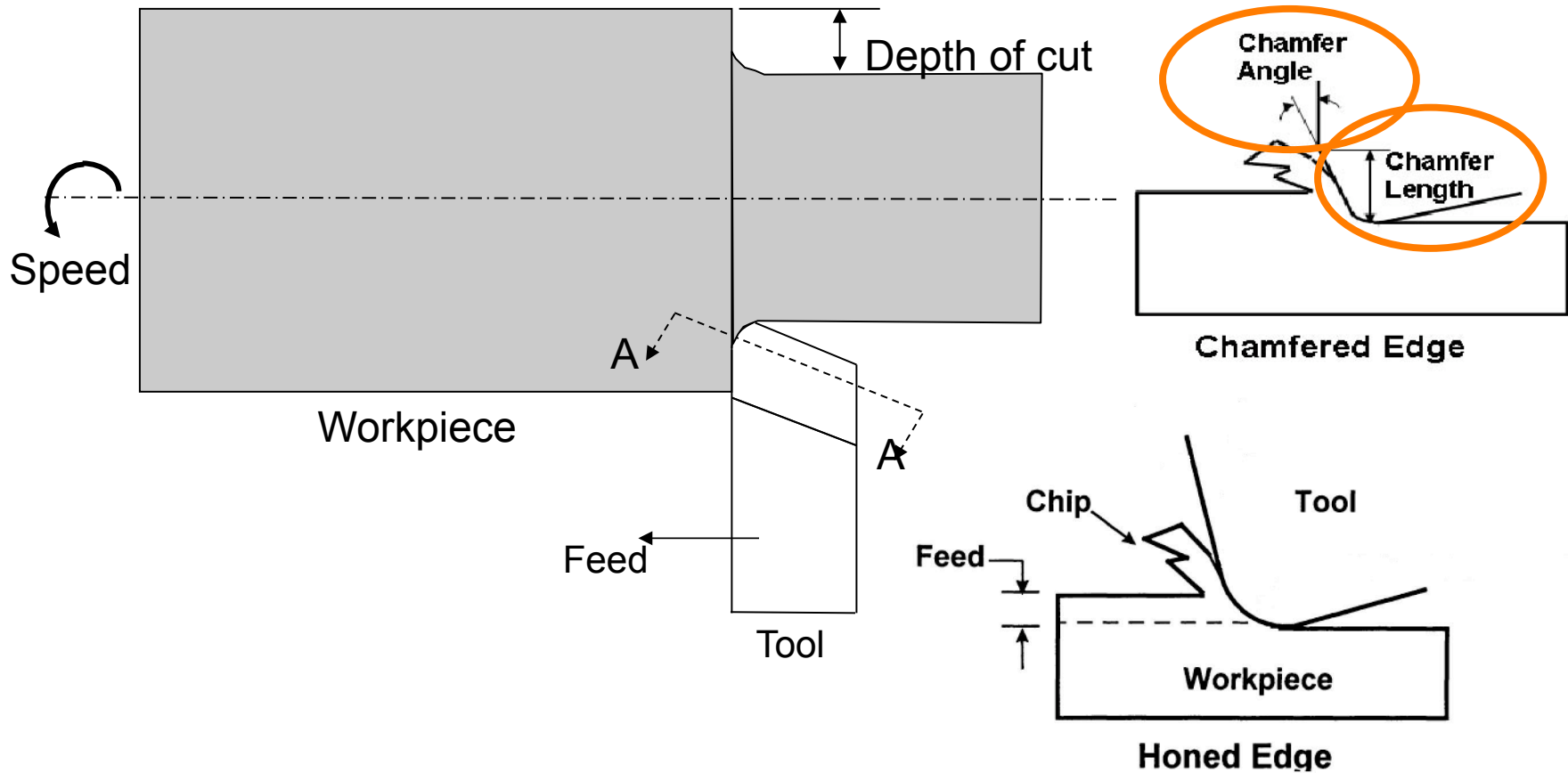
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Motivating Example: Hard Turning



- Objective: minimize cutting force

Motivating Example: Hard Turning



- Objective: minimize cutting force

Branching and Nested Factors

- **Nested factor:** A factor that can change with respect to the level of another factor.
- **Branching factor:** A factor within which other factors are nested.

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Hard turning experiment

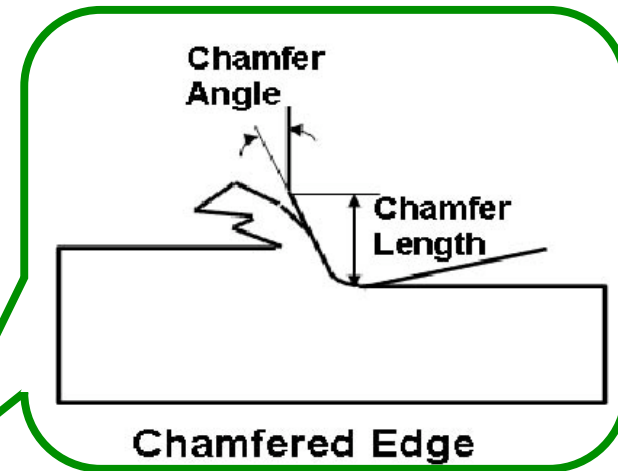
Branching factor	z_1	Tool

Branching and Nested Factors

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Hard turning experiment

Branching factor	z_1	Tool (chamfer)

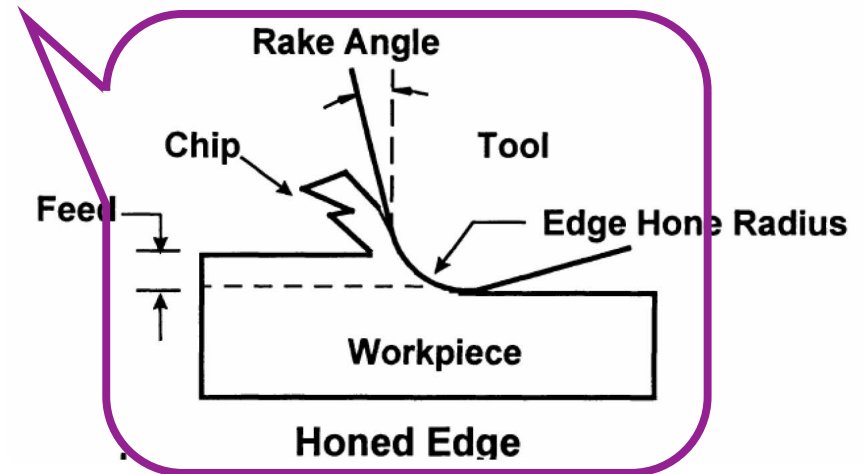
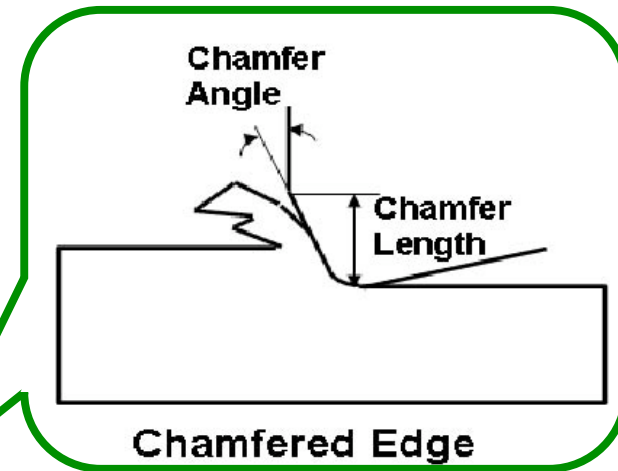


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Hard turning experiment

Branching factor	Z_1	Tool (chamfer & hone)

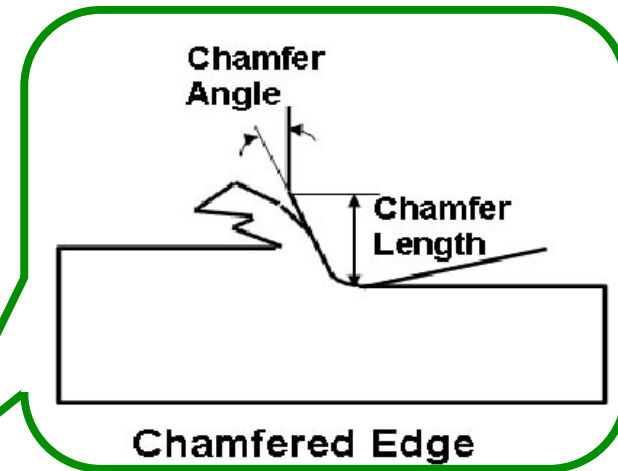


Branching and Nested Factors

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Hard turning experiment

Branching factor	z_1	Tool (chamfer & hone)
Nested factors	$v_1 z_1$ = chamfer $v_2 z_1$ = chamfer	Angle Length

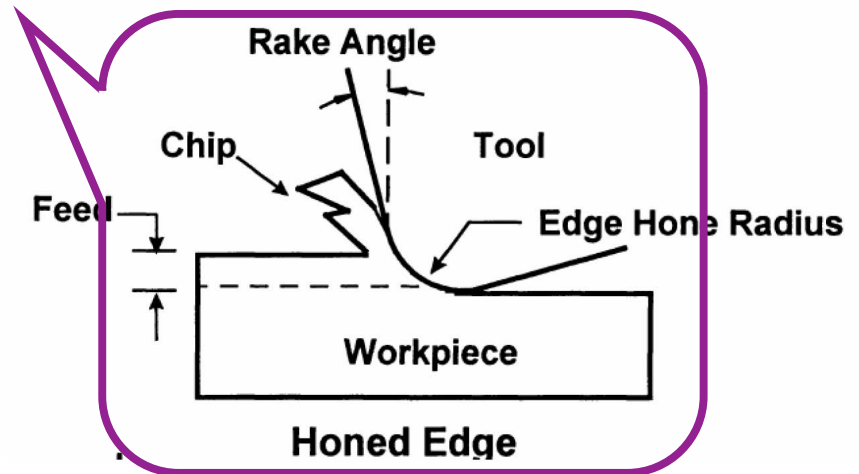
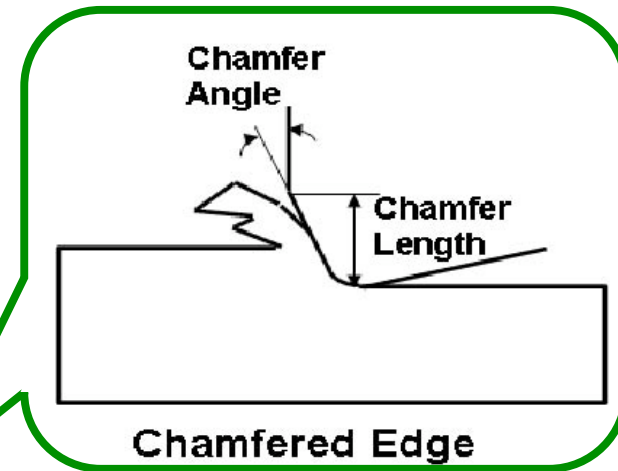


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Hard turning experiment

Branching factor	z_1	Tool (chamfer & hone)
Nested factors	$v_1 z_1 = \text{chamfer}$	Angle
	$v_2 z_1 = \text{chamfer}$	Length
	$v_1 z_1 = \text{hone}$	None
	$v_2 z_1 = \text{hone}$	None



Computer Experiments in Machining

Type of Factor	Notation	Factor	Ranges
Branching factors	z_1	Tool (Cutting edge shape)	chamfer & hone
Nested factors	$v_1 z_1$ = chamfer	Angle	17~ 20
	$v_2 z_1$ = chamfer	Length	115~140
	$v_1 z_1$ = hone	None	None
	$v_2 z_1$ = hone	None	None
Shared factors	x_1	Cutting edge radius	5~25
	x_2	Rake angle	-15 ~ -5
	x_3	Tool nose radius	0.4 ~ 1.6
	x_4	Cutting speed	120 ~ 240
	x_5	Feed	0.05 ~ 0.15
	x_6	Depth of cut	0.1 ~ 0.25

Design with Branching and Nested Factors

- Properties
 - Branching factors are **qualitative**, which cannot be divided into intervals.

Design with Branching and Nested Factors

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Design with Branching and Nested Factors

Printed circuit board
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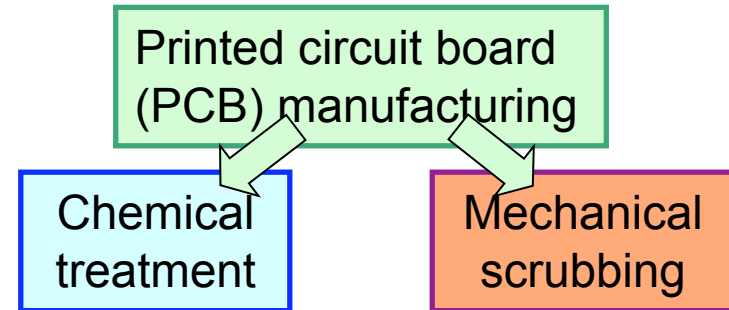
Printed circuit board
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Two surface preparation methods

Design with Branching and Nested Factors

- Properties

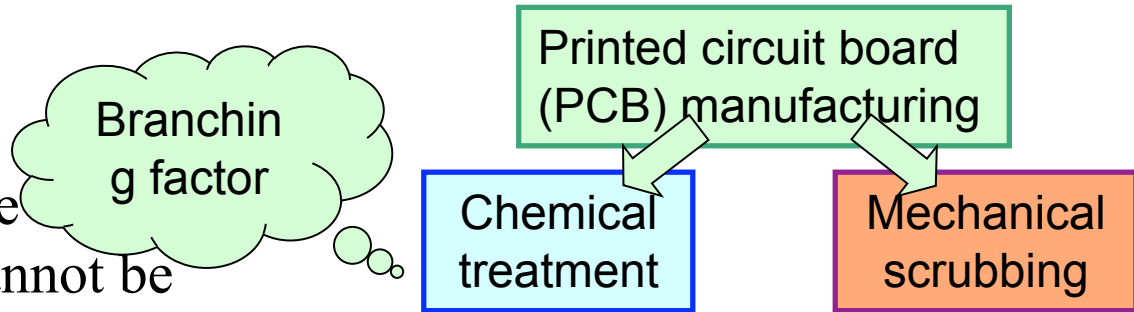
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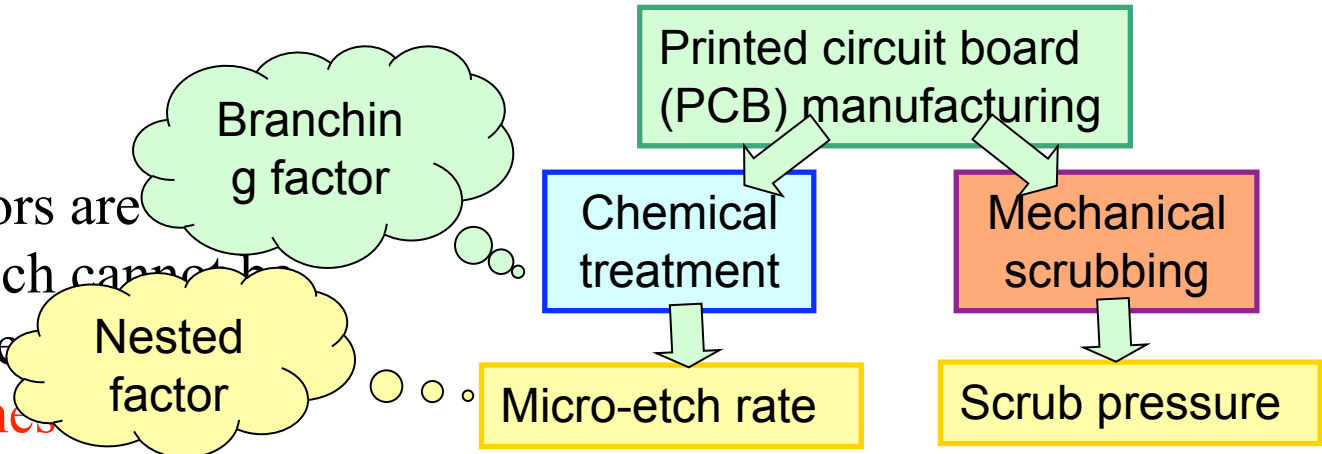
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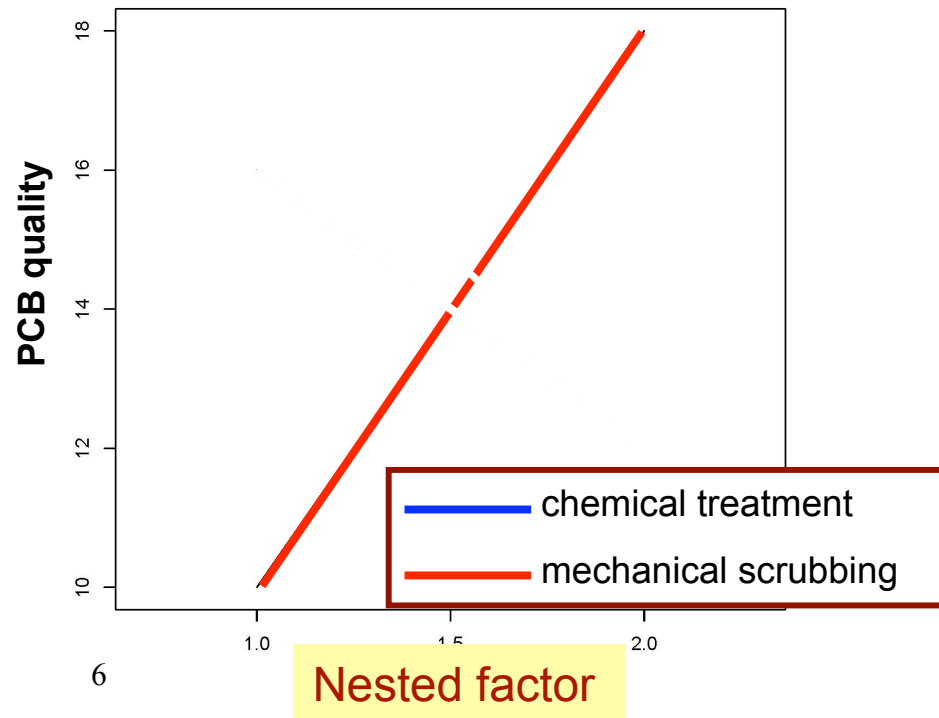
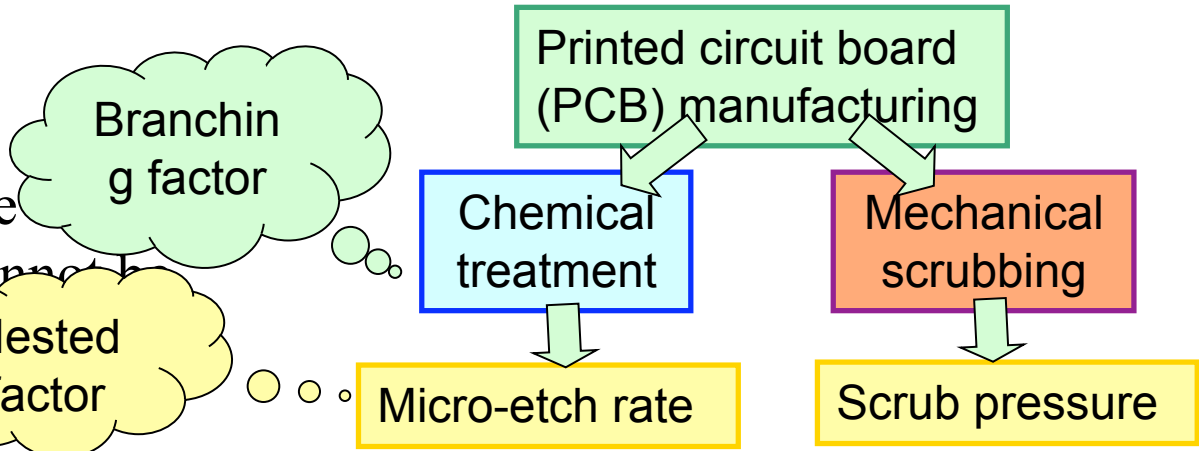
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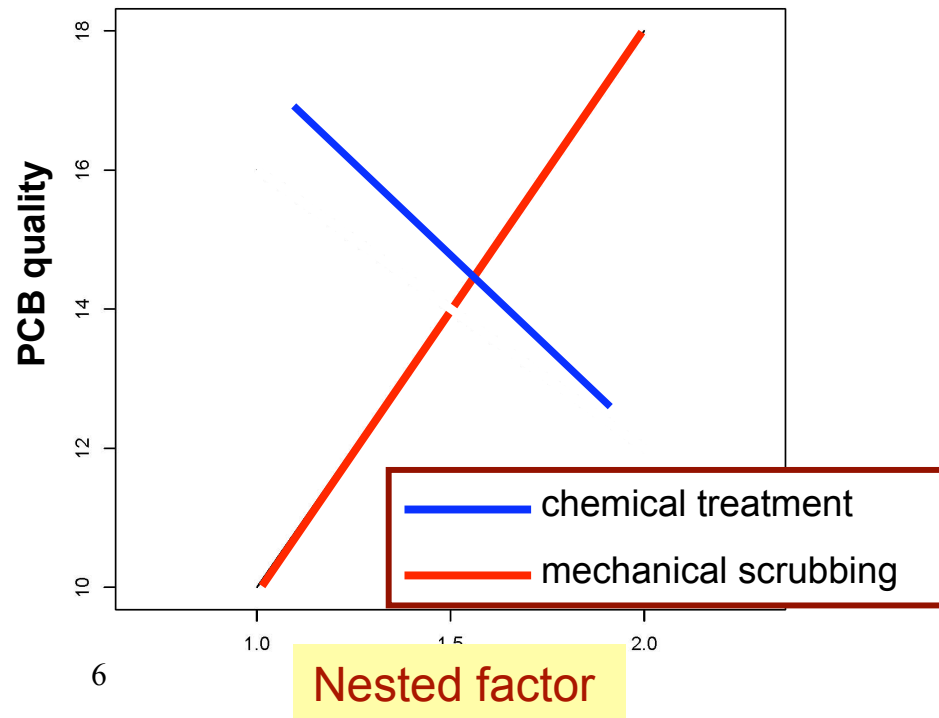
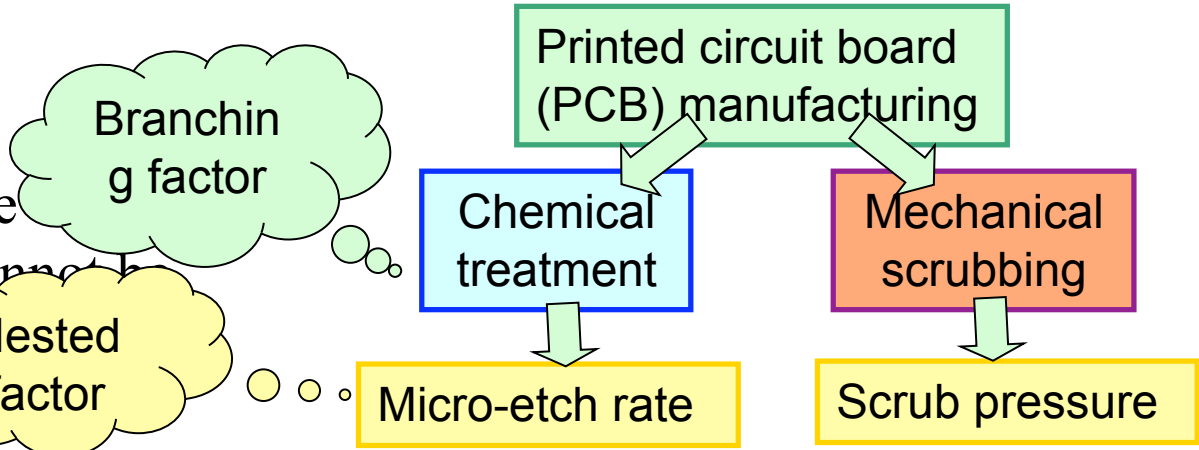
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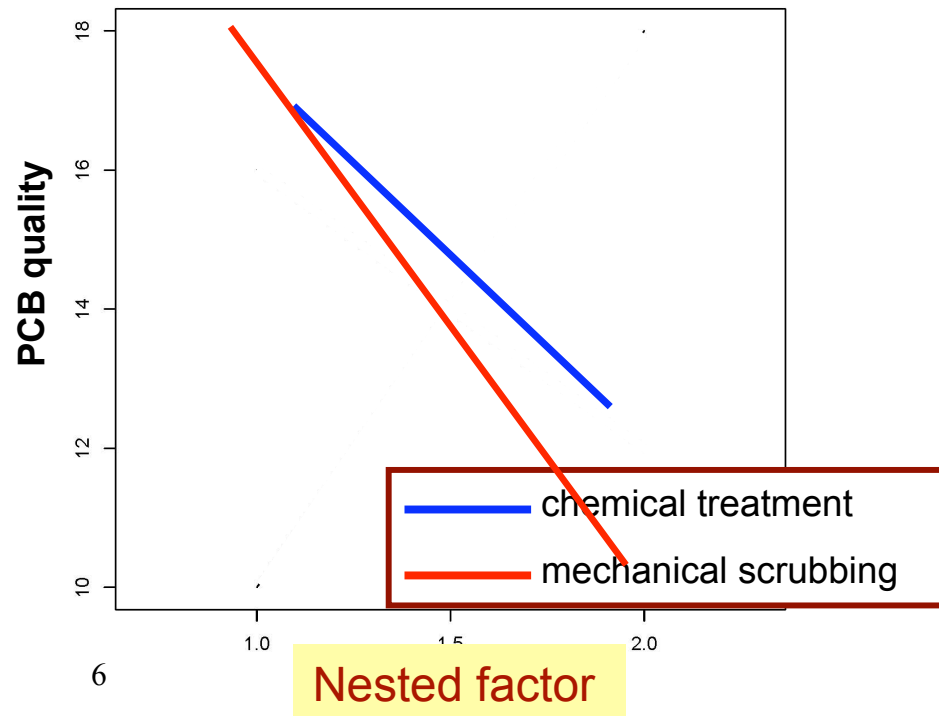
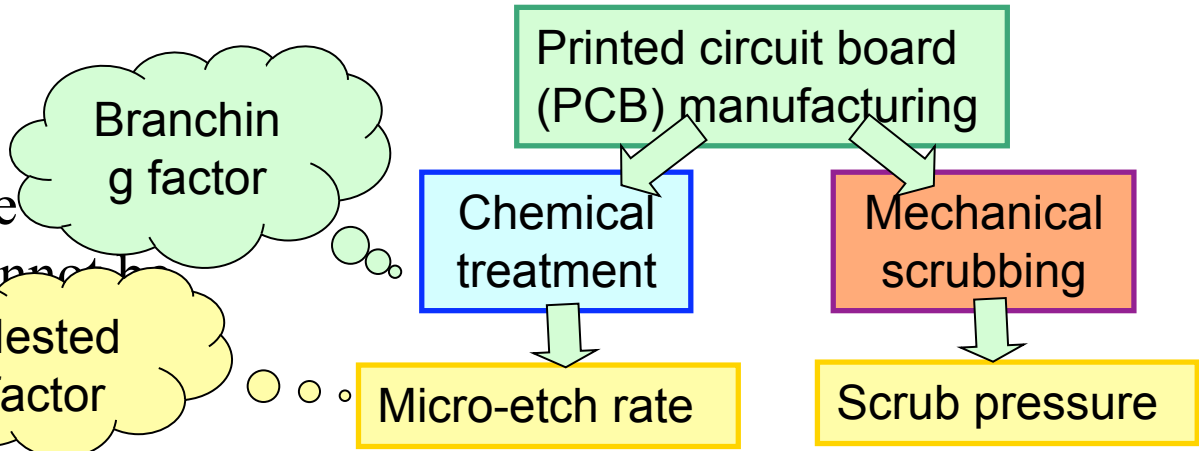
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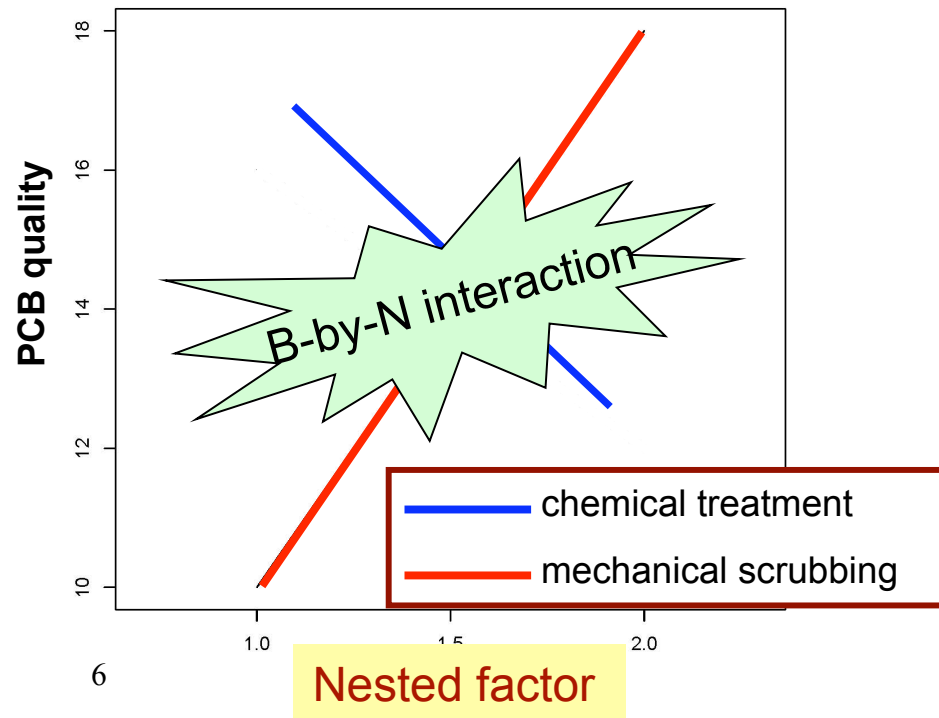
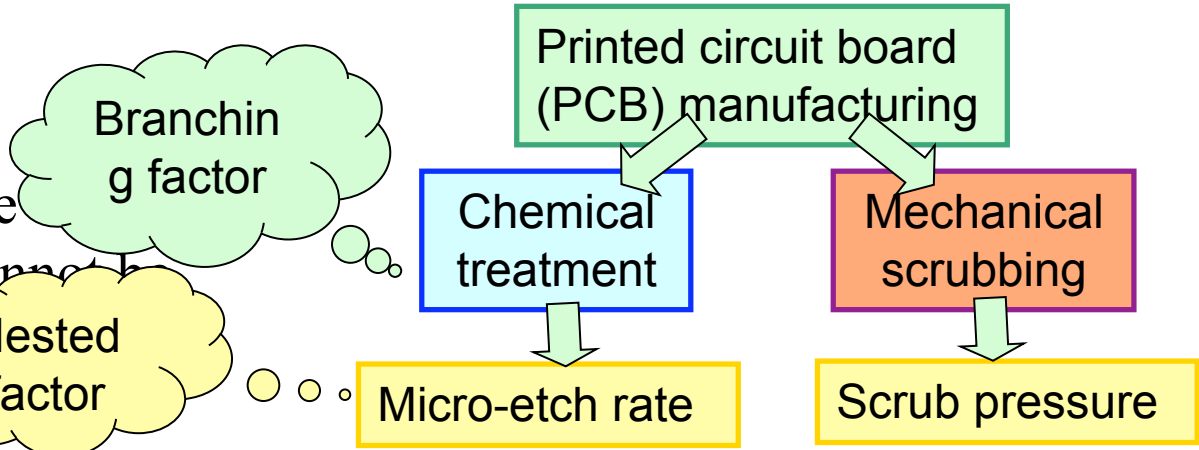
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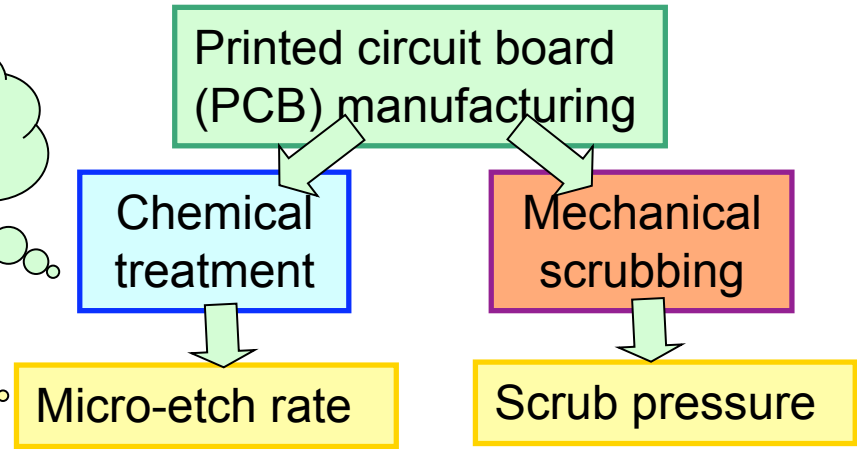
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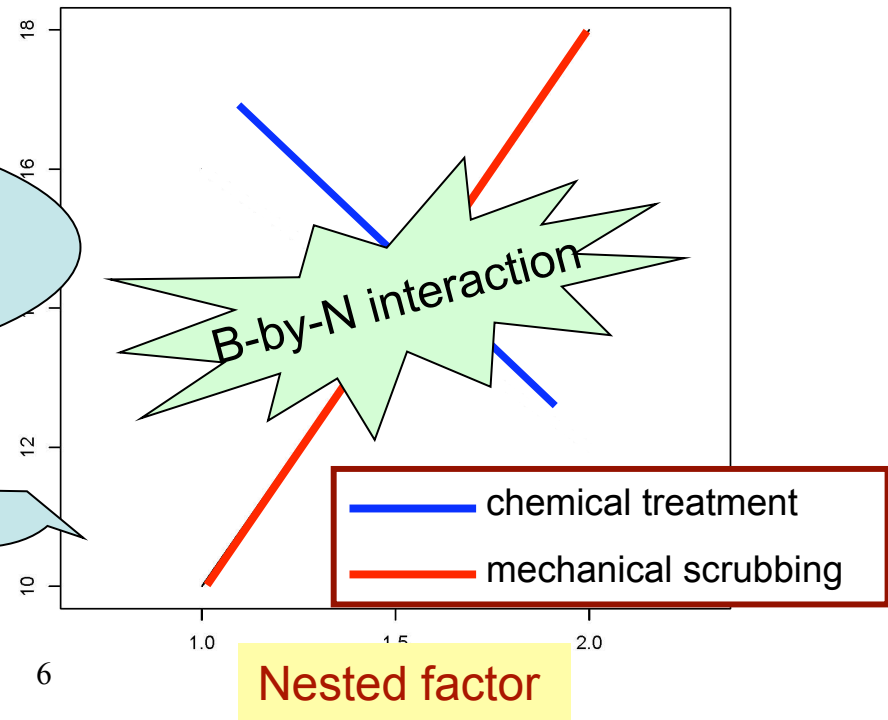
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Branching factor

Nested factor



Any main effect correlated with this B-by-N interaction will be misspecified.



Computer Experiments with Branching and Nested Factors

- Branching and nested factors (Phadke, 1989; Taguchi, 1987).
- Challenges in design:
 - Involve both quantitative and qualitative factors.
 - Some two-factor interactions are important.
- Challenges in modeling:
 - No correlation function defined for nested factors.
- First work on design and analysis of computer experiments with branching and nested factors.

Computer Experiments with Branching and Nested Factors

- Branching and nested factors (Phadke, 1989; Taguchi, 1987).
- Challenges in design:

No existing design can be applied directly.

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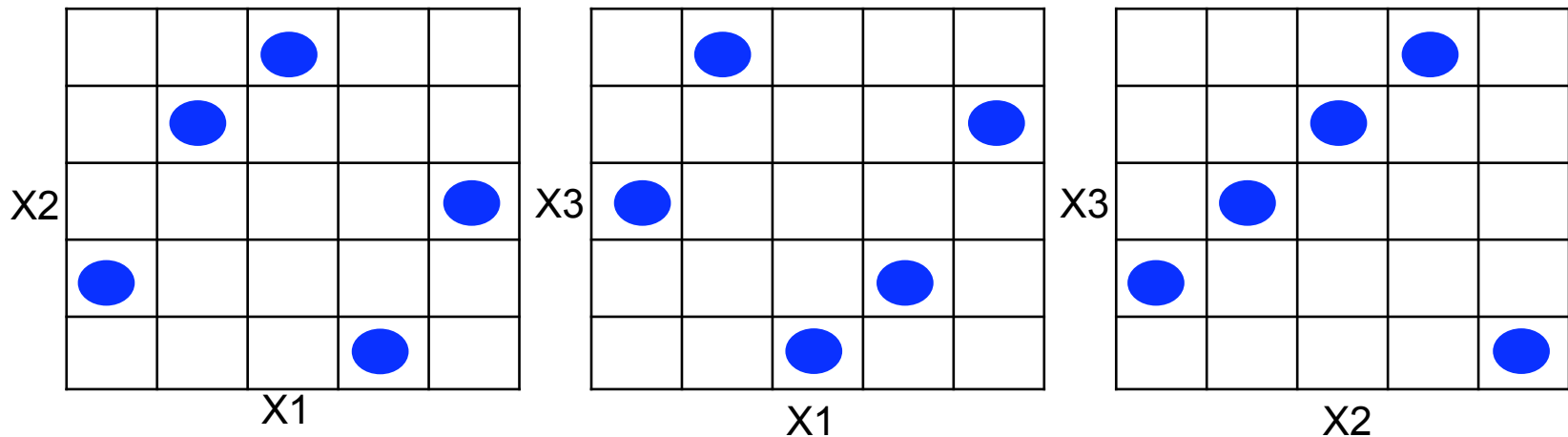
No suitable model available.

- First work on design and analysis of computer experiments with branching and nested factors.

Design of Computer Experiments with Branching and Nested Factors

- Latin hypercube design (LHD).
 - McKay, Beckman, Conover (1979).
 - Easy to construct.
 - One-dimensional balance.
- **LHD cannot be applied directly.**

run	X1	X2	X3
1	1	2	3
2	2	4	5
3	3	5	1
4	4	1	2
5	5	3	4



A Naïve Design

run	z_1	v_1	v_m	x_1	x_t
	1	Nested factors			Shared factors		
	.						
	.						
	1						
	2						
	.						
	.						
	2						

Branching factors

Nested factors

Shared factors

A Naïve Design

run	z_1	$v_1 \dots v_m$	$x_1 \dots x_t$
1	1	LHD ($n_1, m+t$)	
·	·		
·	·		
·	·		
n_1	1		
n_1+1	2	LHD ($n_1, m+t$)	
·	·		
·	·		
·	·		
$2n_1$	2		

A Naïve Design

run	z_1	v_1 v_m	x_1 x_t
1	1		
·	·		
·	·		
·	·		
n_1	1		
n_1+1	2		
·	·		
·	·		
·	·		
$2n_1$	2		

LHD ($n_1, m+t$)

replicates are
wasteful

LHD ($n_1, m+t$)

A Naïve Design

run	z_1	v_1	v_m	x_1 x_t
1	1				
⋮	⋮				
n_1	1				
⋮	⋮				
⋮	⋮				
⋮	⋮				
$2n_1$	2				

LHD ($n_1, m+t$)

LHD ($n_1, m+t$)

n_1 large

replicates are wasteful

Branching Latin Hypercube Design (BLHD)

run	Z_1	$V_1 \dots\dots V_m$	$X_1 \dots\dots X_t$
1	1		
.	.		
.	.		
.	.		
n_2	1		
n_2+1	2		
.	.		
.	.		
.	.		
$2n_2$	2		

Branching Latin Hypercube Design (BLHD)

run	z_1	$v_1 \dots v_m$	$x_1 \dots x_t$
1	1		<div style="border: 2px solid orange; padding: 5px; display: inline-block;">LHD ($2n_2, t$)</div>
.	.		
.	.		
.	.		
n_2	1		
n_2+1	2		
.	.		
.	.		
.	.		
$2n_2$	2		

Branching Latin Hypercube Design (BLHD)

run	z_1	$v_1 \dots v_m$	$x_1 \dots x_t$
1	1		
·	·	LHD (n_2, m)	LHD ($2n_2, t$)
·	·		
·	·		
n_2	1		
n_2+1	2		
·	·	LHD (n_2, m)	
·	·		
·	·		
$2n_2$	2		

Branching Latin Hypercube Design (BLHD)

run	z_1	$v_1 \dots v_m$	$x_1 \dots x_t$
1	1		
⋮	⋮		
n_2	1	LHD (n_2, m)	
n_2+1	2		LHD ($2n_2, t$)
⋮	⋮	LHD (n_2, m)	
⋮	⋮		
⋮	⋮		
$2n_2$	2		

n_2 smaller

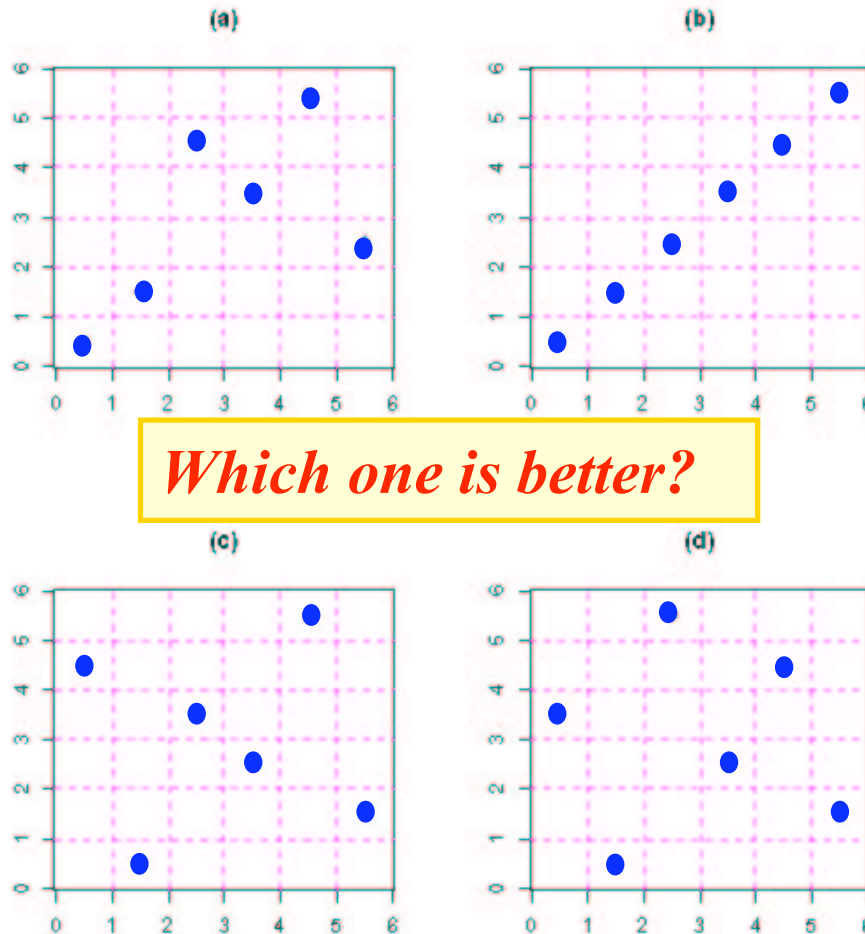
No replicates

Branching Latin Hypercube Design (BLHD)

run	z_1	$V_1 \dots V_{m_1}$	z_2	$V_1 \dots V_{m_2}$	$X_1 \dots X_t$
1	1		1	LHD ($N/2, m_2$) first half	
·	·	LHD ($N/2, m_1$)			
·	·		1	LHD ($N/2, m_2$) first half	
·	1				LHD (N, t)
·	2		2	LHD ($N/2, m_2$) second half	
·	·	LHD ($N/2, m_1$)			
·	·		2	LHD ($N/2, m_2$) second half	
N	2				

How to Find a “Good” Design?

- For n runs and k factors, we can obtain $(n!)^k$ LHDs.



Minimize Correlation

- Iman and Conover (1982), Owen (1994), and Tang (1998) proposed to find designs minimizing correlations among factors.
- Owen (1994)

$$\rho^2 = \frac{\sum_{i=2}^k \sum_{j=1}^{i-1} \rho_{ij}^2}{k(k-1)/2},$$

where ρ_{ij} is the linear correlation between columns i and j .

- Figure (c) shows the optimal LHD found by Tang (1998).

Maximize Minimum Distance

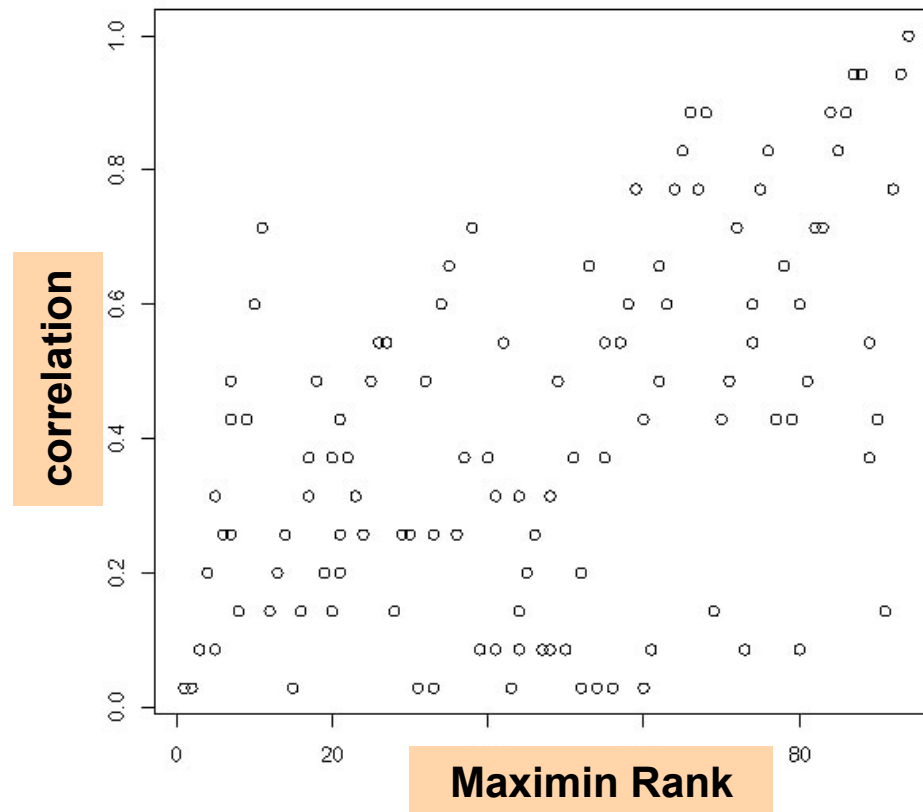
- Johnson, Moore, and Ylvisaker (1990) proposed the maximum distance criterion, which maximizes the minimum inter-site distance.
- Morris and Mitchell (1995) proposed to find the best LHD by maximizing the minimum distance between the points.
- Use a scalar-valued function to rank competing designs.

$$\phi_p = \left(\sum_{i=1}^{\binom{n}{2}} \frac{1}{d_i^p} \right)^{1/p}$$

- ✓ d_i is the (rectangular or Euclidean) distance between two design points.

Motivating Example

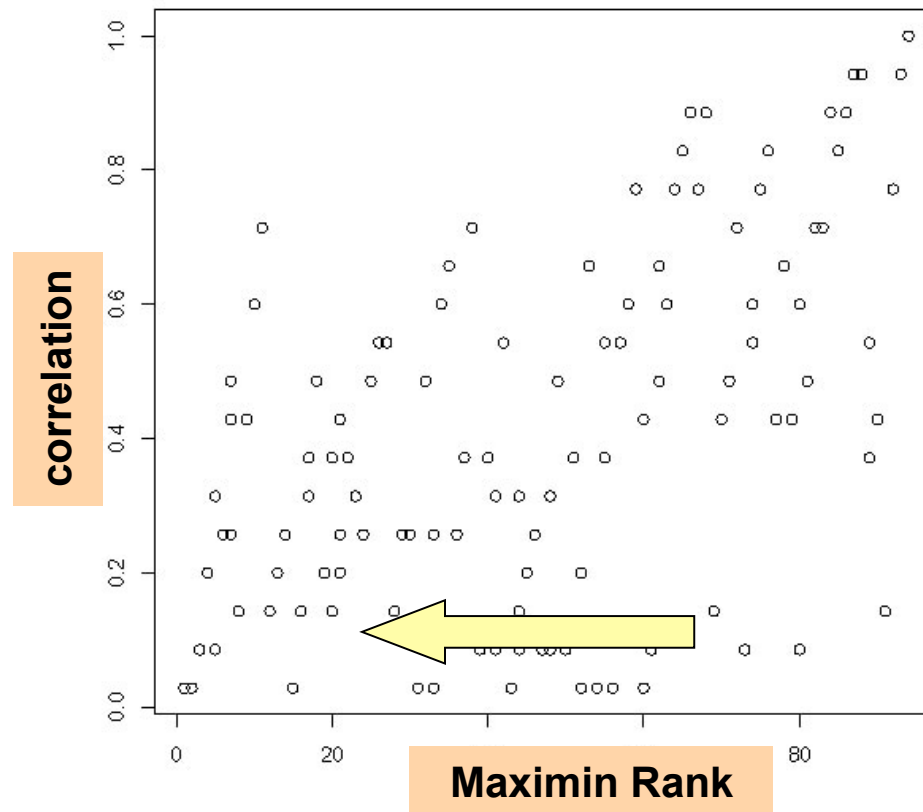
- Maximin rank vs. correlation in $n=6, k=2$ case.



- These two criteria can give conflicting results.
- Minimization of one criterion may not lead to minimization of the other.

Motivating Example

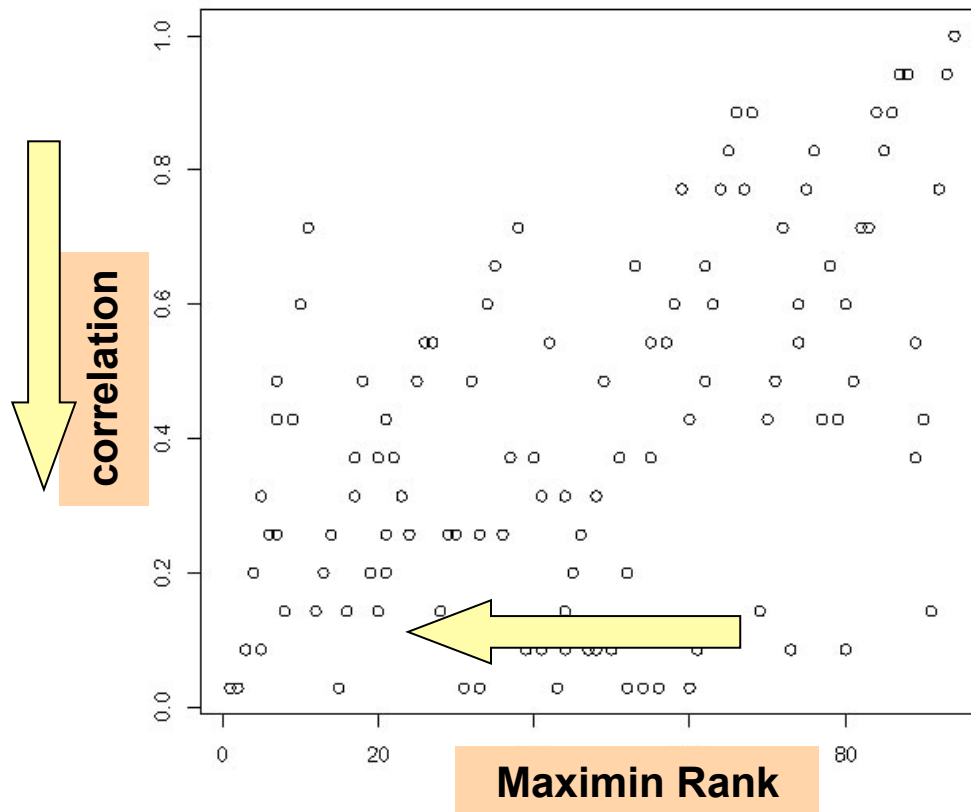
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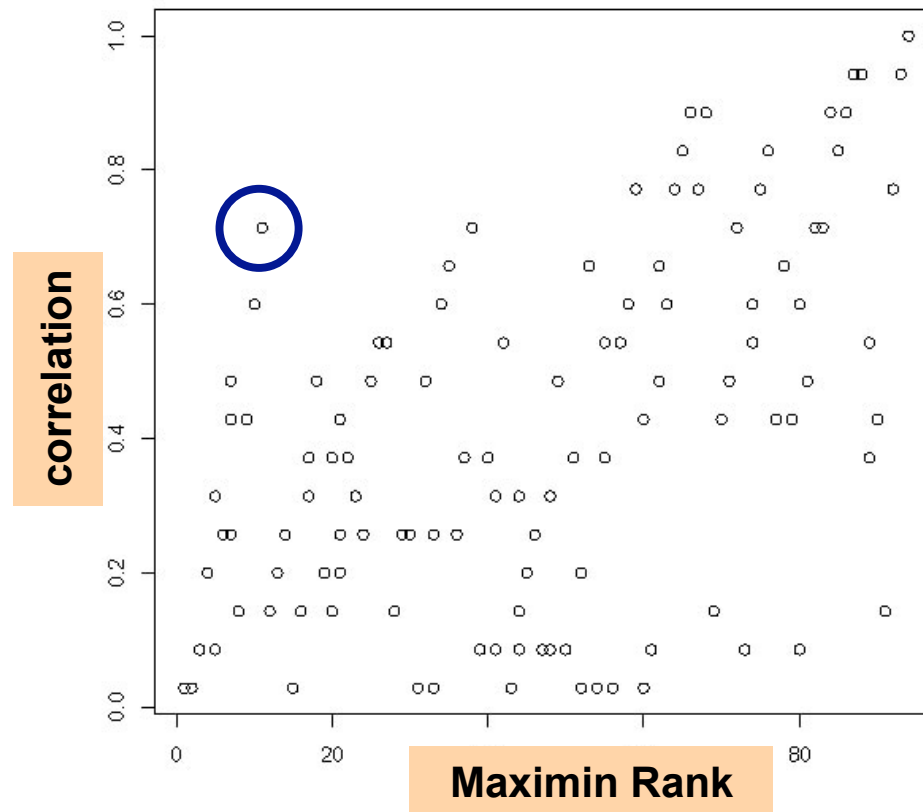
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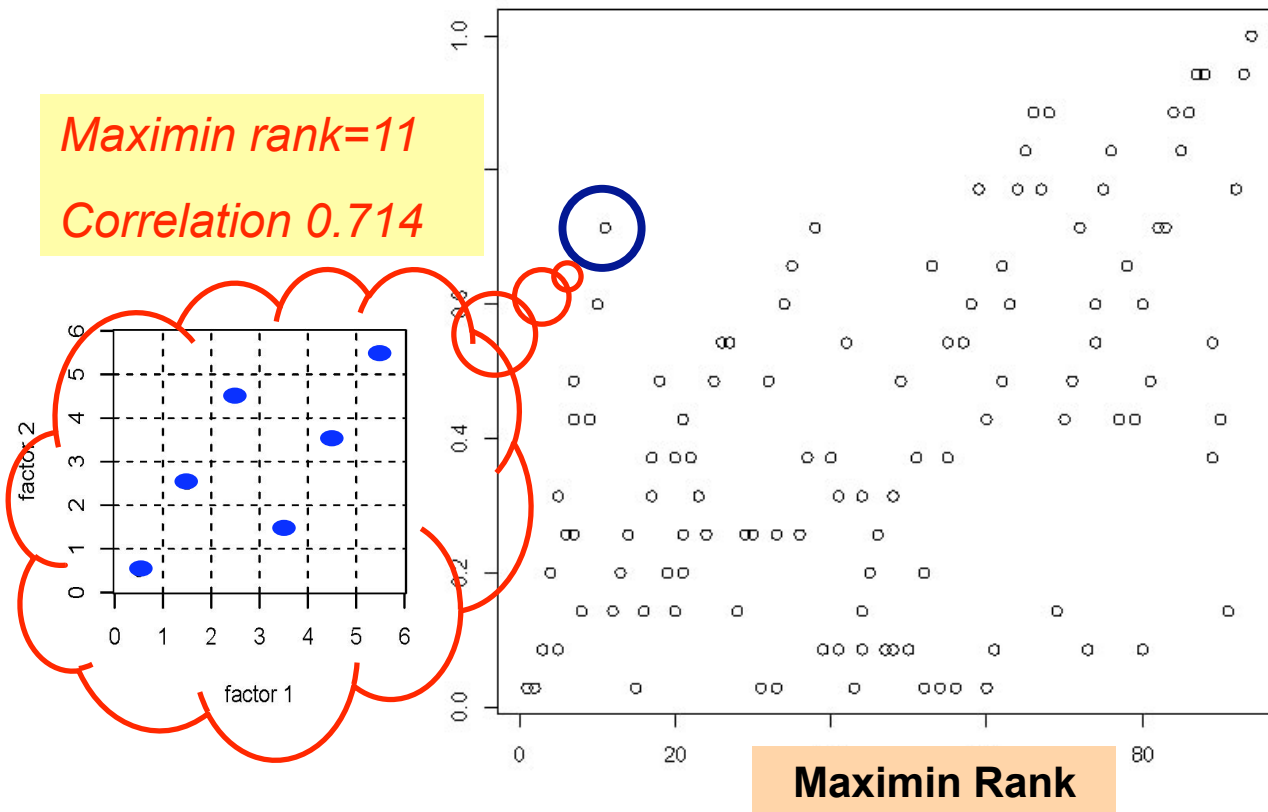
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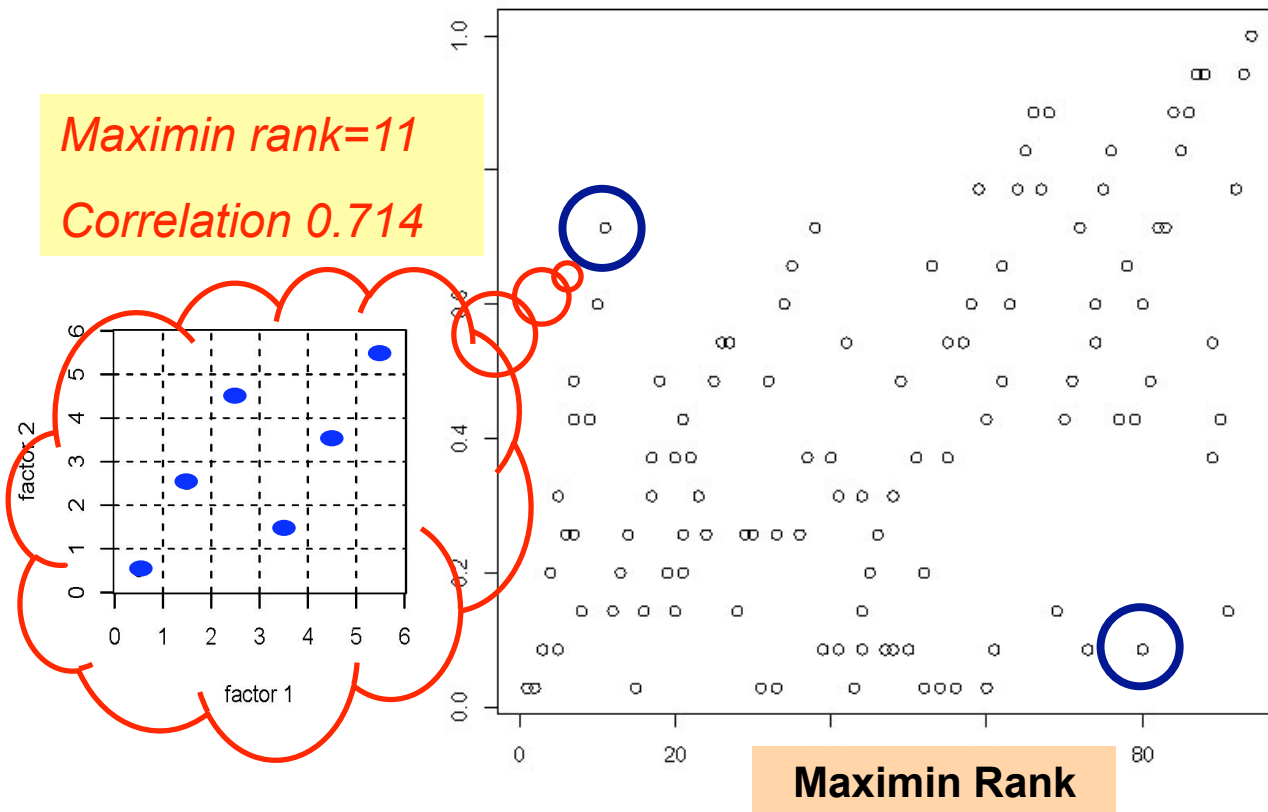
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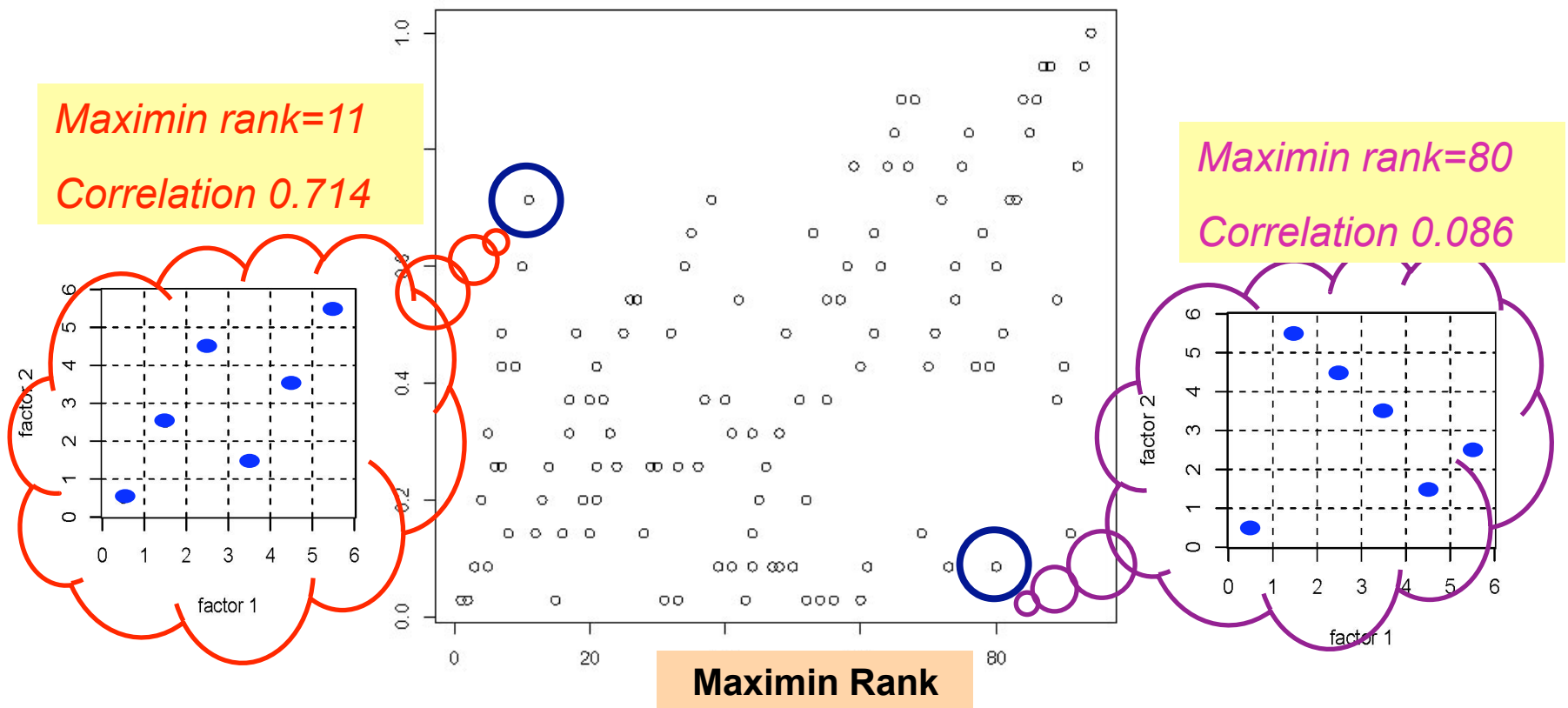
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Orthogonal-Maximin Latin Hypercube Design

- Our objective is to find an LHD that minimizes both ρ^2 and ϕ_p .
- **Proposition 1:** For an $LHD(n, k)$, $\phi_{p,L} \leq \phi_p \leq \phi_{p,U}$.

$$\phi_{p,L} = \left\{ \binom{n}{2} \left(\frac{\lceil \bar{d} \rceil - \bar{d}}{\lceil \bar{d} \rceil^p} + \frac{\bar{d} - \lfloor \bar{d} \rfloor}{\lfloor \bar{d} \rfloor^p} \right) \right\}^{1/p} \quad \text{and} \quad \phi_{p,U} = \left\{ \sum_{i=1}^{n-1} \frac{(n-i)}{(ik)^p} \right\}^{1/p}.$$

- Define

$$\psi_p = w\rho^2 + (1-w) \frac{\phi_p - \phi_{p,L}}{\phi_{p,U} - \phi_{p,L}},$$

where $w \in (0, 1)$.

- A design that minimizes ψ_p is called an orthogonal-maximin Latin hypercube design (OMLHD).

Reference: V. Roshan Joseph and Ying Hung (2008). Orthogonal-Maximin Latin Hypercube Designs, *Statistica Sinica*, 18, 171-186.

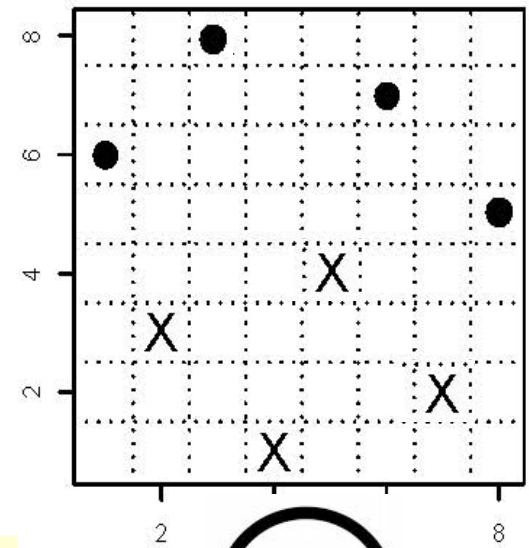
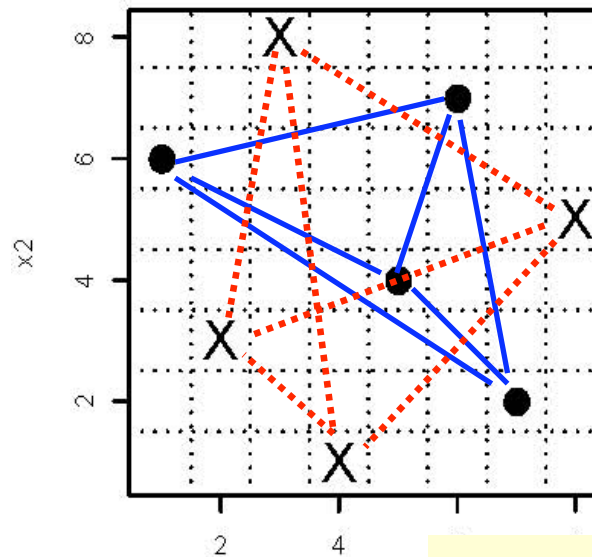
Orthogonal-Maximin BLHD

- Orthogonal-Maximin BLHD

$$\rho^2 = \frac{\sum_{i=2}^p \sum_{j=1}^{i-1} \rho_{ij}^2 + \sum_{i=1}^t \sum_{j=1}^{\alpha} \tilde{\rho}_{ij}^2}{(p(p-1)/2) + \alpha t},$$

$$\Rightarrow \phi_P = \left(\sum_{g \neq h} \left[\frac{t}{d_x(\mathbf{g}, \mathbf{h})} \right]^P + \sum_{i=1}^{k_1} \sum_{g_{t+1}=h_{t+1}=z_{1,i}} \left[\frac{1+t}{d_{v_1}(\mathbf{g}, \mathbf{h}) + d_x(\mathbf{g}, \mathbf{h})} \right]^P \right)^{1/P},$$

run	z_1	v_1	x_1	x_2
1	1	1	4	1
2	1	2	3	8
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X : $z_1=1$ • : $z_1=2$



Orthogonal-Maximin BLHD

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- **Proposition 2:**

$$\phi_{P,L} = 6\kappa \left[t(N^2 - 1) + \sum_{i=1}^{k_1} m_1(n_1^2 - 1) \right]^{-1},$$

$$\phi_{P,U} = N \left[\sum_{i=1}^{k_1} \sum_{j=1}^{n_1-1} \frac{(n_1 - j)(t + m_1)^P}{j^P (t + k_1 m_1)^P} + \sum_{j=1}^{N-1} \frac{N - j}{j^P} \right]^{1/P}.$$

Orthogonal-Maximin BLHD

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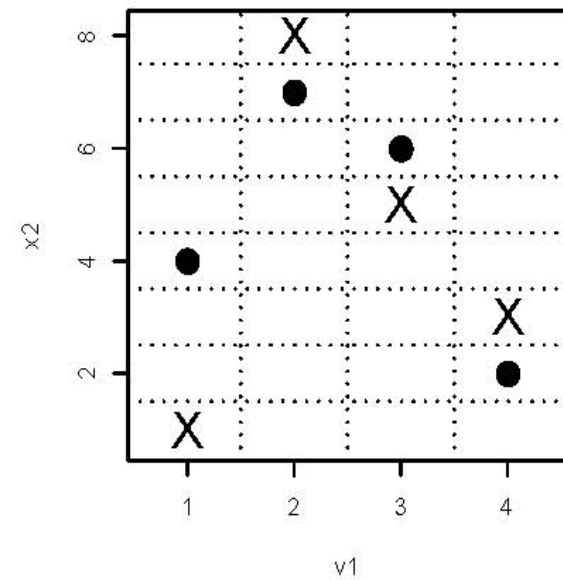
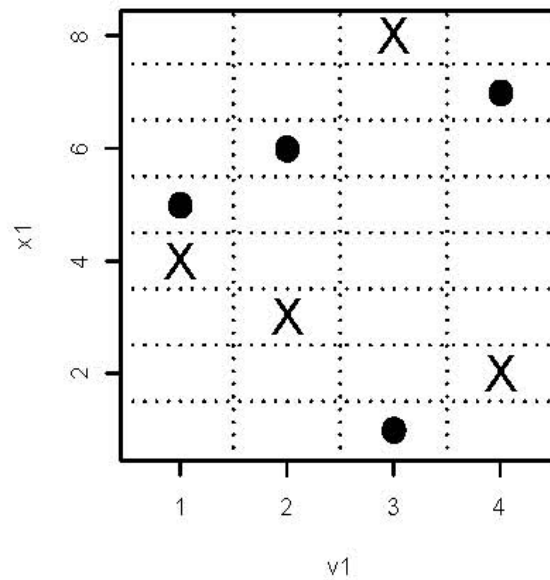
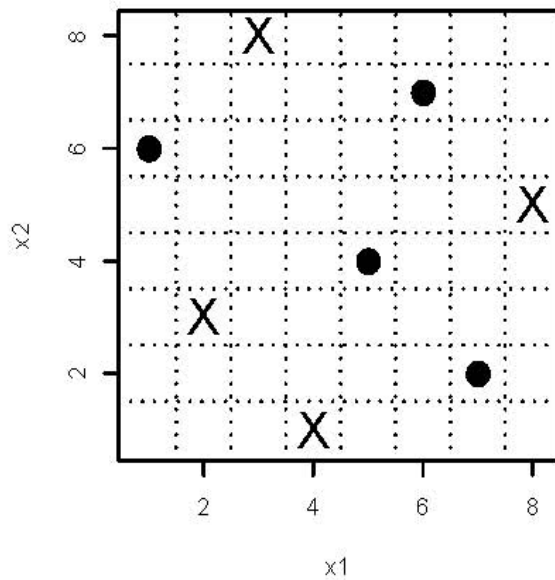
- A multi-objective criterion is to minimize

$$\psi_P = w\rho^2 + (1 - w) \frac{\phi_P - \phi_{P,L}}{\phi_{P,U} - \phi_{P,L}}.$$

- Heuristic algorithm: **simulated annealing algorithm(SAA)**

Orthogonal-Maximin BLHD Example

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1	1	1	4	1
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3	1	3	8	5
4	1	4	2	3
5	2	1	7	2
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7	2	3	6	7
8	2	4	5	4



Model Fitting in Computer Experiments

- Kriging is first developed 40 years ago by G. Matheron and named in honor of D. Krige.
- Kriging is widely used in the analysis of computer experiments (Sacks et al. 1989; Santner et al. 2003) and in spatial statistics.
- Interpolating metamodel.
 - Interpolation property essential for *deterministic* computer experiments.
- Efficient in higher dimensions.

New Kriging Model with Branching and Nested Factors

- Kriging:

$$Y(\mathbf{x}) = \mathbf{v}(\mathbf{x})' \mu_m + Z(\mathbf{x}),$$

$Z(\mathbf{x})$ is assumed to be a weak stationary stochastic process with mean 0 and covariance function $\sigma_m^2 \psi$

- Product correlation function:

$$\triangleright \mathbf{w}_1 = (x_{11}, x_{12}, z_{11}, v_{11}^{z_{11}}), \mathbf{w}_2 = (x_{21}, x_{22}, z_{21}, v_{21}^{z_{21}}).$$

$$\triangleright \text{cor}(\mathbf{Y}(\mathbf{w}_1), \mathbf{Y}(\mathbf{w}_2)) :$$

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- Gaussian correlation function for shared factors:

$$\psi(\mathbf{h}) = \exp\left(-\sum_{j=1}^p \theta_j h_j^2\right).$$

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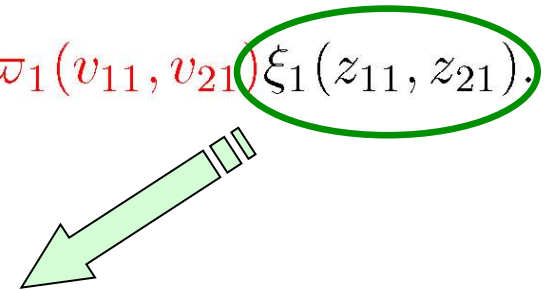
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- Isotropic correlation for the branching factors:

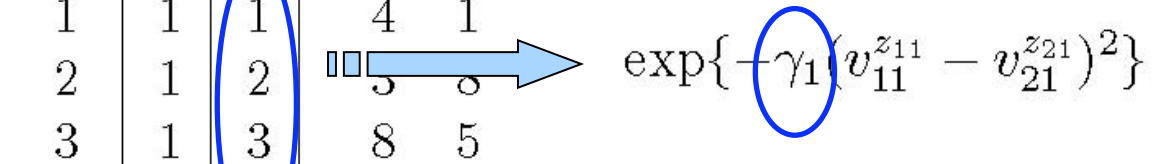
$$\xi_1(z_{11}, z_{21}) = \exp \left\{ -\theta_1 I_{[z_{11} \neq z_{21}]} \right\}.$$

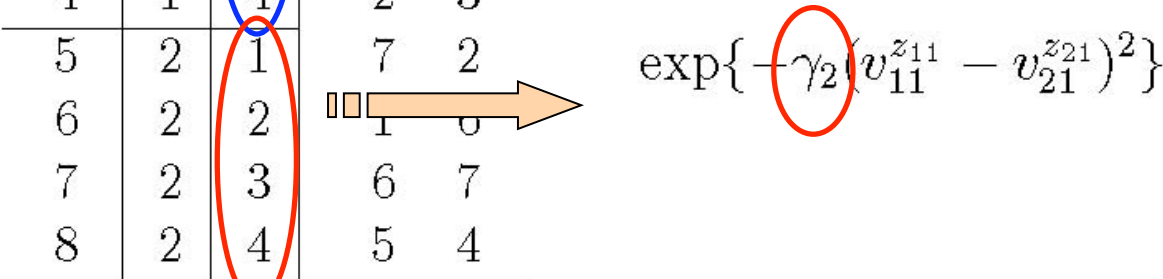


New correlation function for the nested factors

- Why not $\psi(\mathbf{h}) = \exp(-\sum_{j=1}^p \theta_j h_j^2)$.

run	z_1	v_1	x_1	x_2
1	1	1	4	1
2	1	2	5	8
3	1	3	8	5
4	1	4	2	3
5	2	1	7	2
6	2	2	1	8
7	2	3	6	7
8	2	4	5	4





- Define new correlation function for nested factors:

$$\varpi_1(v_{11}^{z_{11}}, v_{21}^{z_{21}}) = \exp\left\{-\sum_{j=1}^2 \gamma_j (v_{11}^{z_{11}} - v_{21}^{z_{21}})^2 I_{[z_{11}=z_{21}=j]}\right\}.$$

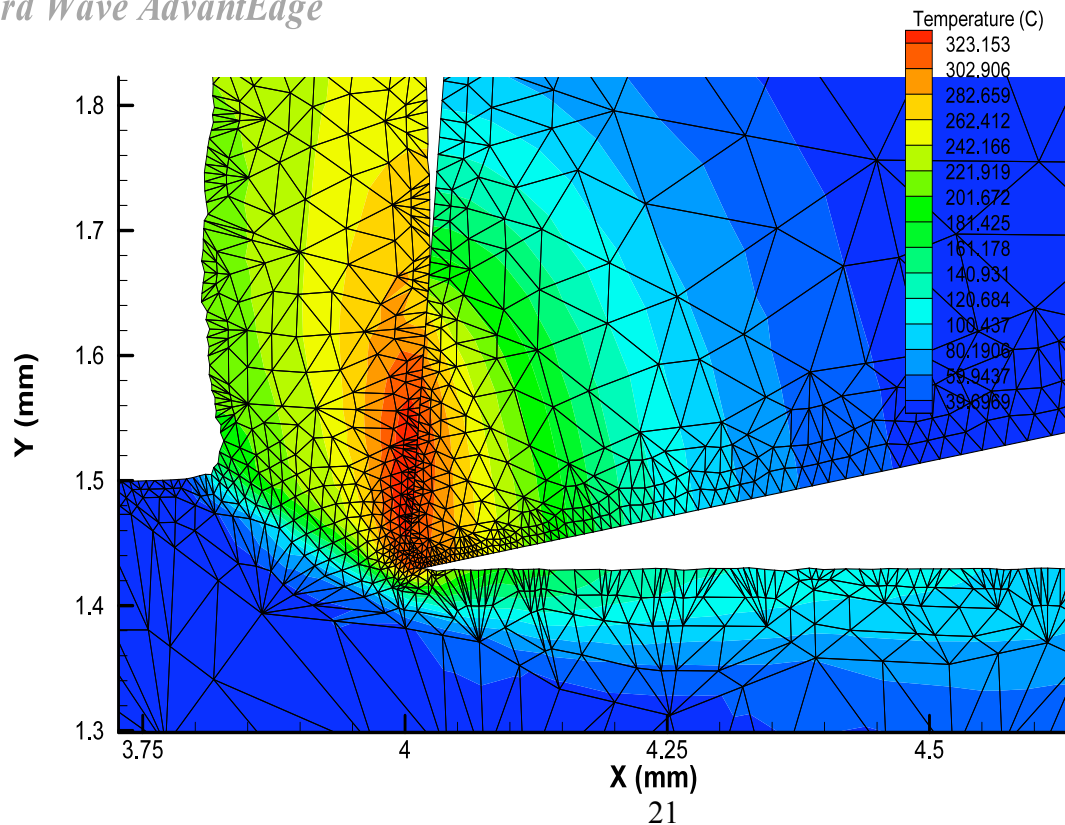
Computer Experiments in Machining

Type of Factor	Notation	Factor	Ranges
Branching factors	z_1	Tool (Cutting edge shape)	chamfer & hone
Nested factors	$v_1 z_1$ = chamfer	Angle	17~ 20
	$v_2 z_1$ = chamfer	Length	115~140
	$v_1 z_1$ = hone	None	None
	$v_2 z_1$ = hone	None	None
Shared factors	x_1	Cutting edge radius	5~25
	x_2	Rake angle	-15 ~ -5
	x_3	Tool nose radius	0.4 ~ 1.6
	x_4	Cutting speed	120 ~ 240
	x_5	Feed	0.05 ~ 0.15
	x_6	Depth of cut	0.1 ~ 0.25

Finite Element Based Simulation in Machining

- Hard turning experiments are simulated from *AdvantEdge*
- Time consuming: 12 hrs ~1 day per run

Third Wave AdvantEdge



Finite Element Based Simulation in Machining

Run	z_1	v_1	v_2	x_1	x_2	x_3	x_4	x_5	x_6	force
1	1	1	6	15	23	7	9	18	10	162.1
2	1	2	11	25	3	25	14	25	19	284.9
3	1	3	3	4	20	18	18	5	26	160.3
4	1	4	14	9	6	6	27	7	17	121.1
5	1	5	8	16	8	21	2	2	1	104.6
6	1	6	1	17	10	5	25	19	25	241.9
7	1	7	12	29	26	15	5	14	12	195.4
8	1	8	5	26	16	30	22	15	6	159.5
9	1	9	15	7	13	26	7	11	27	241.6
10	1	10	10	1	29	20	23	6	5	88.33
11	1	11	2	20	21	27	10	20	29	320.4
12	1	12	7	8	11	14	4	29	21	218.8
13	1	13	13	22	9	1	24	27	9	193.5
14	1	14	4	10	2	24	28	13	13	198.6
15	1	15	9	28	25	13	17	3	28	155.1
16	2			19	5	9	1	8	20	164.4
17	2			14	28	17	6	21	24	323.6
18	2			6	17	4	16	12	4	109.1
19	2			11	1	12	15	4	8	115.4
20	2			27	22	8	30	24	16	254.8
21	2			21	14	23	19	10	22	217.0
22	2			23	18	22	12	28	3	243.7
23	2			3	27	3	3	26	14	131.5
24	2			13	15	19	29	16	30	258.7
25	2			24	12	2	11	1	18	109.3
26	2			18	24	28	8	17	2	174.8
27	2			12	30	11	26	9	11	157.0
28	2			2	4	16	13	30	15	133.1
29	2			30	7	10	20	23	7	210.1
30	2			5	19	29	21	22	23	273.3

Computer Experiments in Machining

- Fitted kriging model:

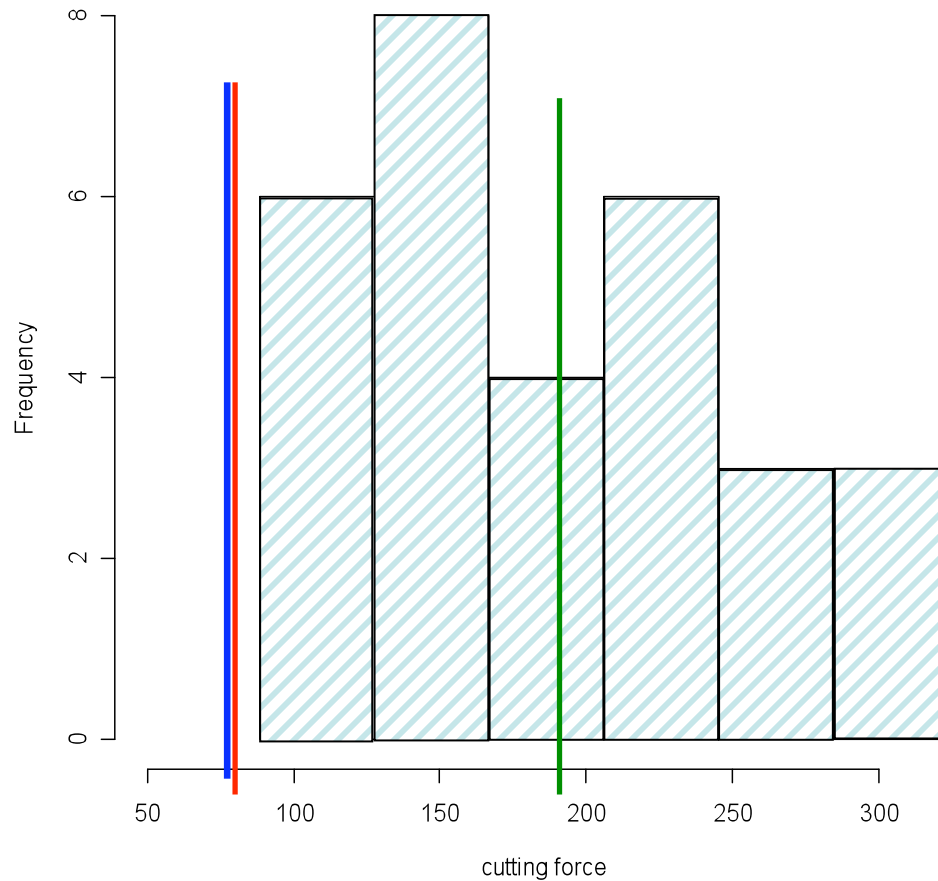
$$\hat{y}(\mathbf{w}) = 5.1 + 0.2x_{51} + 0.2x_{61} - 0.12x_{11}x_{61} + \hat{\psi}(\mathbf{w})' \hat{\Psi}^{-1}(\mathbf{y} - \mathbf{V}_3 \hat{\mu}_3).$$

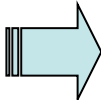
- Optimal setting:

Factors	setting
Cutting edge shape	Chamfer angle: 18.74, length 128.13
Cutting edge radius	5
Rake angle	-13.8
Tool nose radius	1.41
Cutting speed	222
Feed	0.067
Depth of cut	0.123

Computer Experiments in Machining

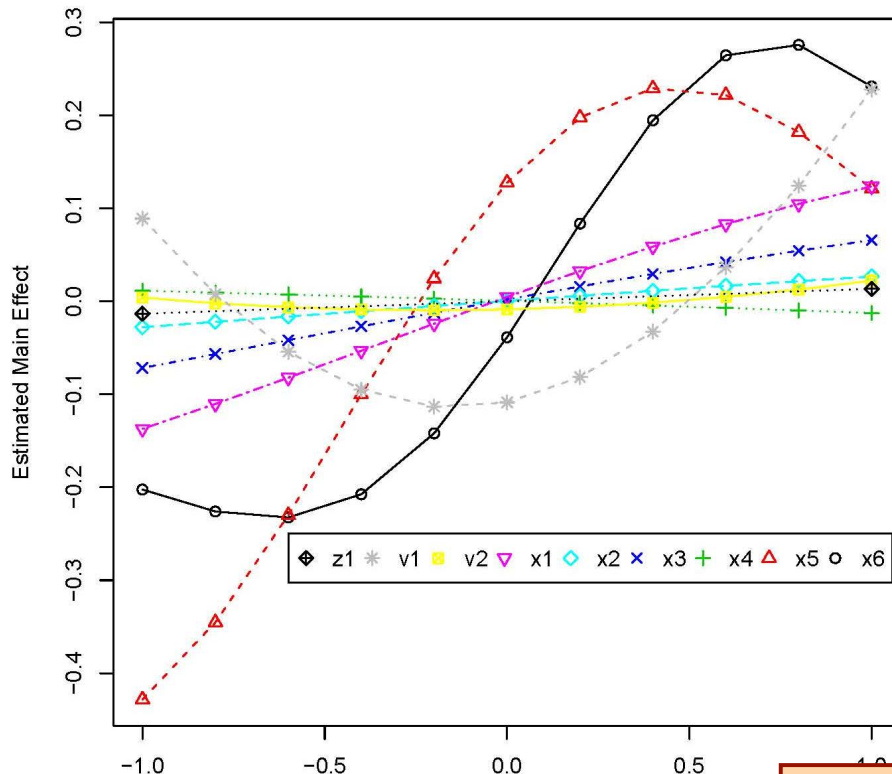
histogram of observed cutting force



- Predicted minimum cutting force: 81 N (Lower than 191N, the observed average)
- Confirmation experiments: 79 N  Confirms the validity of the optimal setting.

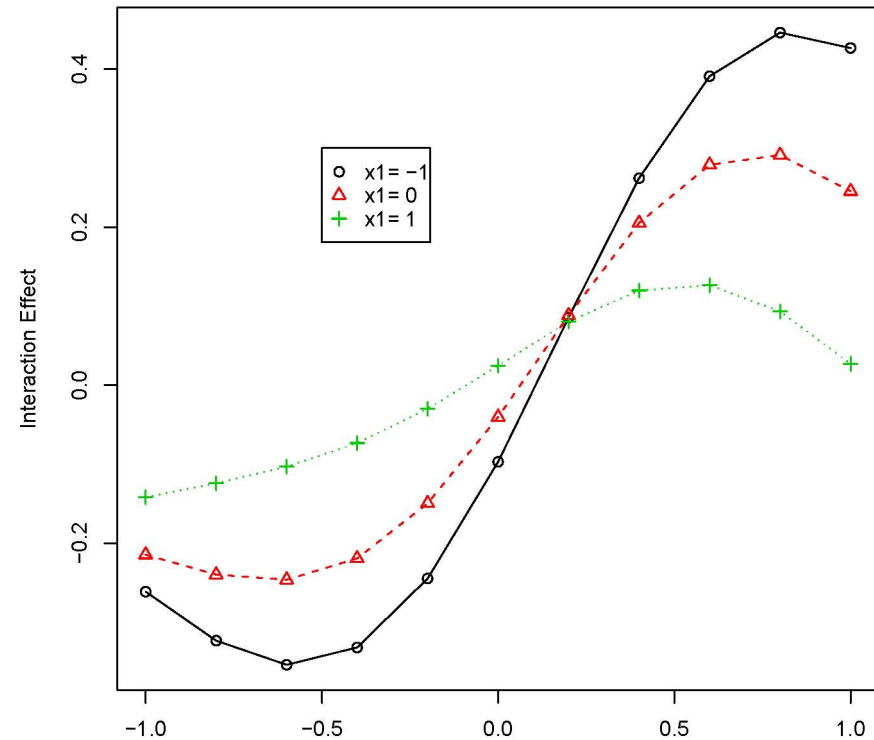
Sensitivity Analysis

Main effects plot



**Feed, depth of cut
have significant effects**

Interaction:
cutting edge radius & depth of cut



For small CER, increase of DOC produces increase of material deformation through shear

Concluding Remarks

- The first work in computer experiments with branching and nested factors.
- A new class of design, branching Latin hypercube design (BLHD), is proposed and optimal criteria are discussed.
- New metamodel: blind kriging and new correlation function.
- New method provides an efficient way to find optimal settings of branching factors, nested factors and shared factors simultaneously.

Thank you !